



جامعة حلب
كلية الهندسة المدنية
قسم الهندسة المائية

أثر التدفقات الفيضانية على البحرين في أقينة التصريف المطري

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ندى التنجي

محمد أمين شخال

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34	(Kalinin)	- - -
36	(Muskingum)	- - -
39	(Muskingum-Cunge)	- - -
42		- -
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45	(Atti-Kin)	-	-		
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74		(5-1)
76	16D	(5-2)
76	14D	(5-3)
77	MD	(5-4)
84	16D	(6-1)
85	14D	(6-2)
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21		(2-2)
23		(2-3)
29		(3-1)
30		(3-2)
35		(3-3)
38	X,K	(3-4)
41		(3-5)
53		(3-6)
68		(3-7)
69	(Preissmann)	(3-8)
74		(5-1)
75	ML-2	(5-2)
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(ML-2)

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الفصل الأول

المقدمة

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-١) Steady Flow () :

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-٢) Unsteady Flow () :

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-٣) :

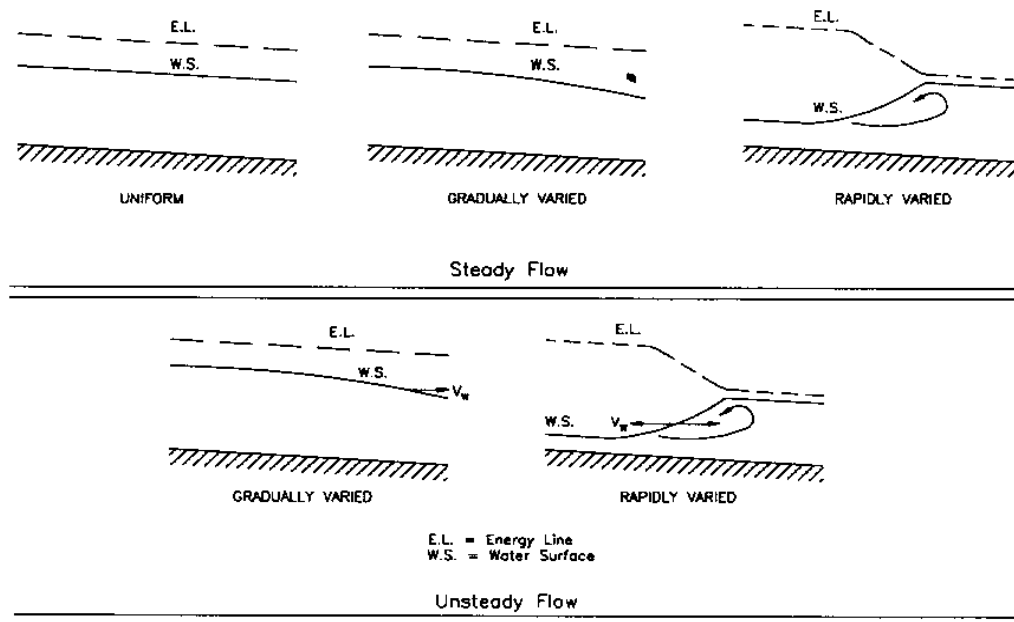
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(1-1).



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Lan Bo 1997 Wang Lan 1996 Cheng Liu

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1996 Zeng Lui 1990 Feng Rui

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Li Jiachun Lin Qingquan Fan Ping

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Kiskin Remando

Kiskin Remando

Visual

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الفصل الثاني

التدفقات المالية

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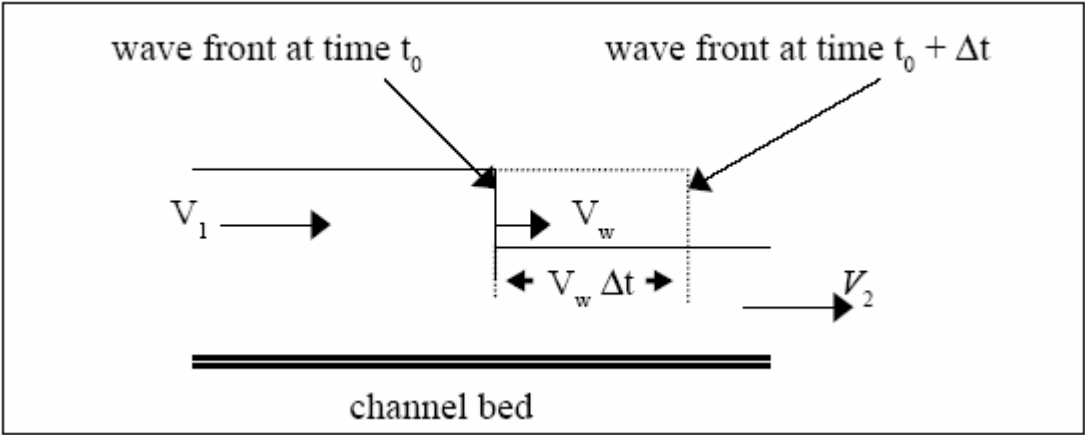
1,2

V_w

$V_2 - V_1$

V_w

$V_2 - V_1$



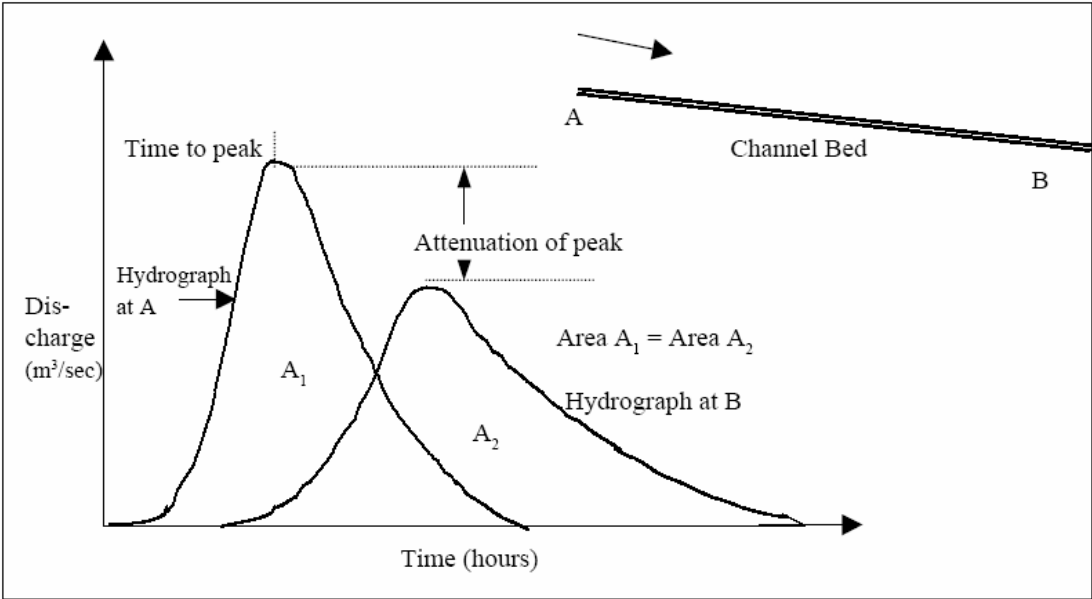
(2-1)

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(2-2)

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$$T_r S_0 \left(\frac{g}{y} \right) \geq 15 \tag{2.1}$$

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.sec : T_r

: S_0

.9.81 m/sec² :g

.m : y

$$\frac{T_r S_0 V_0}{d_0} \geq 85 \tag{2.2}$$

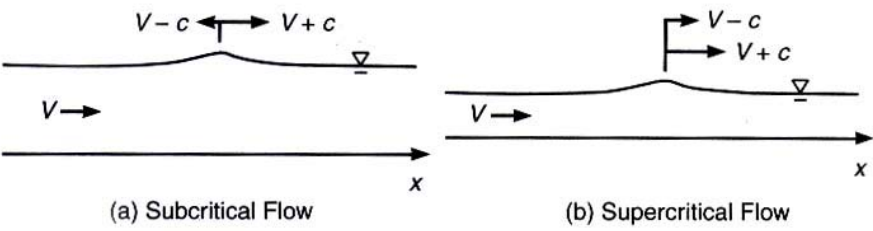
$$:V_0$$

$$(\quad)$$

$$\begin{aligned} & \frac{dx}{dt} \\ &) \\ & \quad \cdot x \qquad V \qquad (2.3) \qquad (\\ &) \qquad (\qquad) \\ & \qquad |V \mp C| \qquad (\\ & \qquad \qquad (gy)^{1/2} \\ & \cdot V/C \qquad F \qquad \frac{dx}{dt} \qquad y \\ & \qquad (dx/dt) \qquad F < 1 \quad V < C \\ & \qquad \qquad V-C \qquad \qquad V + C \\ & \qquad \qquad \qquad (2.4a) \\ & V > C \qquad -V+C \quad V+C \quad - \end{aligned}$$

$$\cdot F > 1$$

$$(\quad)$$



(2-3)

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$(1.7)V_w$

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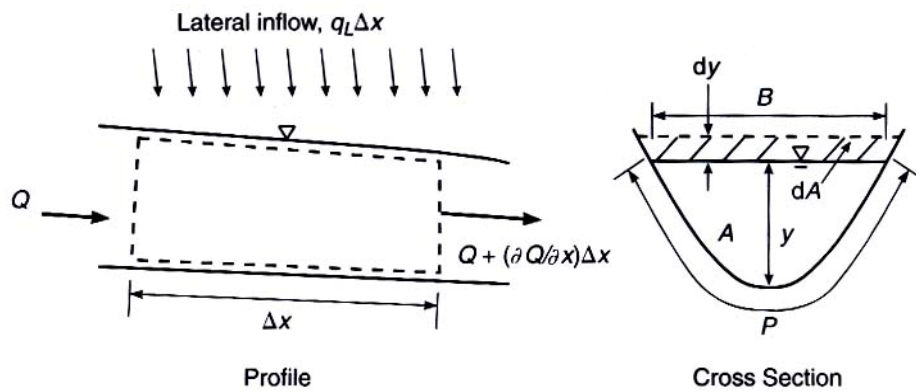
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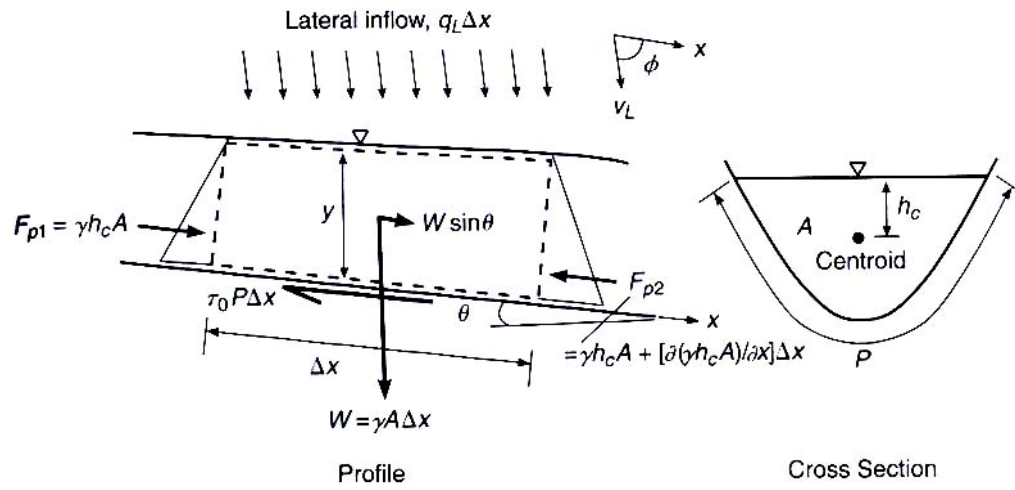
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(3-1)

$$\begin{aligned}
 & \Delta t \\
 & \frac{\partial Q}{\partial x} \Delta x \Delta t - q_l \Delta x \Delta t = -\Delta x \frac{\partial A}{\partial t} \Delta t \\
 & \frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = q_l \\
 & \frac{\partial Q}{\partial x} + B \frac{\partial y}{\partial t} = q_l
 \end{aligned}
 \tag{3.1}$$



(3-2)

(3.2)

$$F_{p1}, F_{p2}$$

W

 Δx

$$F_{p_x} + F_{g_x} - F_{s_x} = \frac{\partial}{\partial t} \left[\int_A \rho V_x \partial A \right] \Delta x + \frac{\partial}{\partial x} \left[\int_A \rho V_x^2 \partial A \right] \Delta x - \rho q_l \Delta x V_l \cos \phi \quad (3.4)$$

 $\cdot X$ $: F_{p_x}$ $\cdot X$ $: F_{g_x}$ $\cdot X$ $: F_{s_x}$ $\cdot X$ $: V_x$ $: q_l$ $\cdot X$ ϕ $: V_l$

$$F_{p_x} = F_{p1} - F_{p2}$$

$$Fp_x=-\frac{\partial}{\partial x}(\gamma h_cA)\Delta x=-\gamma A\frac{\partial y}{\partial x}\Delta x\tag{3.5}$$

$$Ahc=\int_0^{y(x)}[y(x)-\eta]b(\eta)d\eta\tag{3.6}$$

$$=b$$

$$\tag{3.6}$$

$$Fg_x=\gamma A\Delta xS_0\tag{3.7}$$

$$Fs_x=\tau_0p\Delta x\tag{3.8}$$

$$\frac{\partial}{\partial x}\left[\int_A\rho V_x^2\partial A\right]\Delta x=\frac{\partial}{\partial x}[\beta\rho V^2A]\Delta x\tag{3.9}$$


$$\tag{3.9}\tag{3.5}$$

$$\tag{3.10}$$

$$\frac{\partial}{\partial t}\left[\int_A\rho V_x\partial A\right]\Delta x=\rho\frac{\partial}{\partial t}[VA]\Delta x\tag{3.10}$$

$$\rho\Delta x\tag{3.4}\tag{3.9}\tag{3.5}$$

$$\tag{3.10}$$



$$\frac{\partial Q}{\partial t} + \frac{\partial}{\partial x} \left(\beta \frac{Q^2}{A} \right) + \frac{\partial}{\partial x} (\gamma h c A) = gA(S_0 - S_f) + q_l V_l \cos \phi \quad (3.11)$$

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(Inc&Rouse)

(3.2),(3.11)

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(t Q)

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$$I - O = \frac{\Delta S}{\Delta t} \tag{3.2}$$

$$I - O = \frac{\Delta S}{\Delta t} \tag{3.12}$$

$$I - O = \frac{\Delta S}{\Delta t}$$

$$L = \frac{Q \Delta h}{S_0 \cdot dQ} \tag{3.13}$$

$$T = \frac{dV}{dQ} = LB \frac{dh}{dQ} \tag{3.14}$$

$$T = \frac{dV}{dQ} = LB \frac{dh}{dQ}$$

$$T = \frac{dV}{dQ} = LB \frac{dh}{dQ}$$

:

$$Q_A(t + \Delta t) = Q_A(t) + a(Q_Z(t) - Q_A(t)) + b(Q_Z(t + \Delta t) - Q_Z(t))$$

(3.15)

$$a = 1 - e^{-\frac{\Delta t}{T}}$$

(3.16)

$$b = 1 - \frac{T}{\Delta t} a$$

(3.17)

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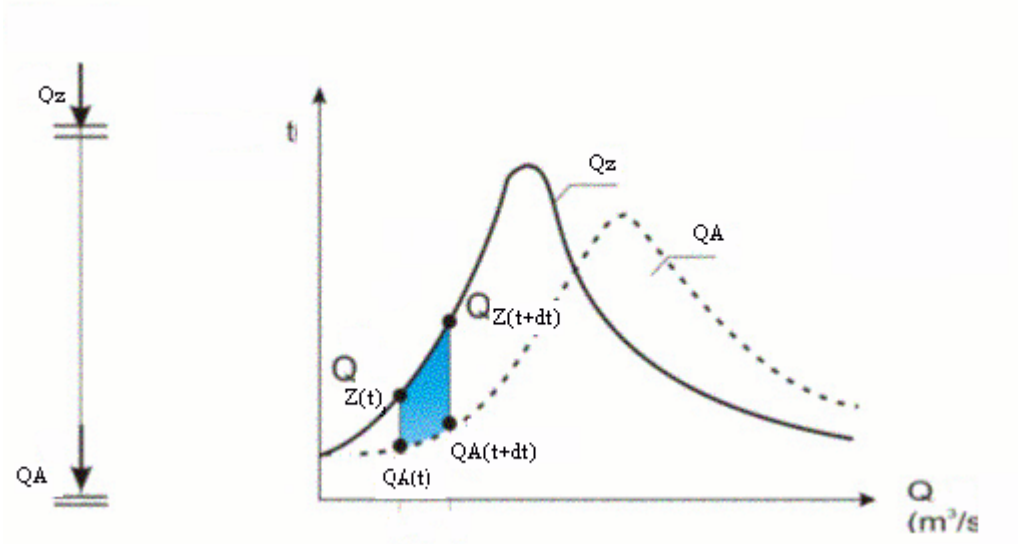
: $Q_A(t)$

: $Q_A(t + \Delta t)$

: $Q_Z(t)$

: $Q_Z(t + \Delta t)$

:



(3-3)

N

N

QA

Qz

. $\Delta t = T$

(Muskingum):

- - -

:

$$\begin{aligned} &\frac{O(t)-O(t-\Delta t)}{2}+K(1-X)\frac{O(t)-O(t-\Delta t)}{\Delta t} \\ &= \frac{I(t)+I(t-\Delta t)}{2}-KX\frac{I(t)-I(t-\Delta t)}{\Delta t} \end{aligned} \tag{3.24}$$

$$O(t)=C_0I(t)+C_1I(t-\Delta t)+C_2O(t-\Delta t) \tag{3.25}$$

$$O_2=C_0I_2+C_1I_1+C_2O_1 \tag{3.26}$$

$$C_0=\frac{-KX-0.5\Delta t}{K-KX+0.5\Delta t} \tag{3.27}$$

$$C_1=\frac{KX+0.5\Delta t}{K-KX+0.5\Delta t} \tag{3.28}$$

$$C_2=\frac{K-KX-0.5\Delta t}{K-KX+0.5\Delta t} \tag{3.29}$$

$$\begin{array}{lll} t_1 & & : I_1 \\ t_2 & & : I_2 \\ t_1 & & : O1 \end{array}$$

$$C_0+C_1+C_2=1 \tag{3.30}$$

. x (1969) Cunge

$$2KX \leq \Delta t \leq \frac{t_p}{5} \tag{3.31}$$

t_p :

X

. X

$$2kx \leq \Delta t \leq 2k(1-x) \tag{3.32}$$

$$\frac{k}{3} \leq \Delta t \leq k \tag{3.33}$$

k

k $.x$

$.k,x$

K, X

X

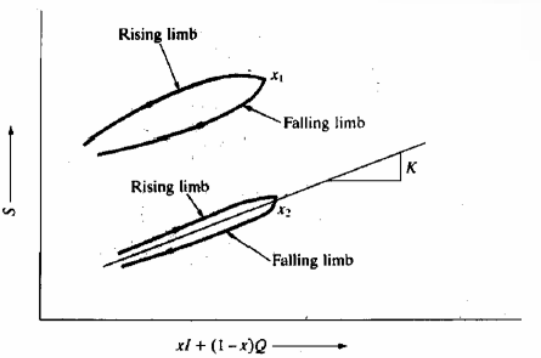
X

$0 - 0.5$

$XI+(1-X)I$

X

$(3-4)$



X,K (3-4)

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$\Delta t < 2KX$ (3.34)

X, K

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$. C_0, C_1, C_2$

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(Muskingum-Cunge):

k,x

$$K = \frac{\Delta L}{V_w} \tag{3.35}$$

$$X = \frac{1}{2} - \frac{Q_0}{2SBV_w\Delta L} \tag{3.36}$$

:K

m^3 / s : Q_0
:S

m :B

m : ΔL

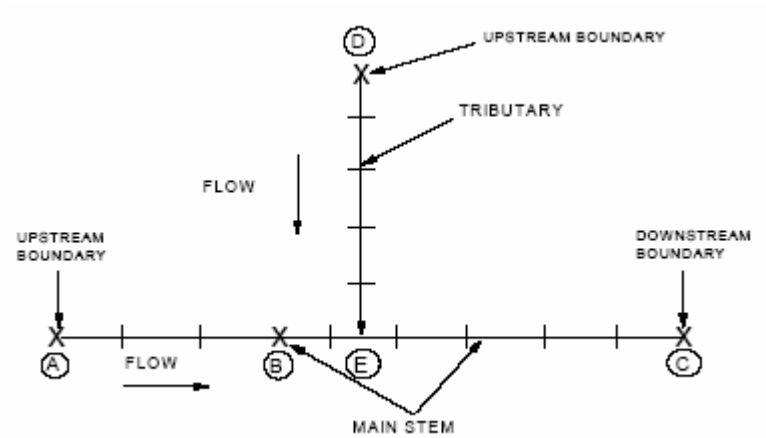
m / s : V_w

.0-0.5 :X

X,K

:

. t m m^2 / sec q



(3-5)

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:

$T_r S(\frac{g}{d_0}) \geq 15$ (3.40)

:

: Tr

.m

: d_0

. $9.81m / \text{sec}^2$

: g

:

$L \leq 0.5 \left[mV_0 \Delta t + \frac{Q_0}{mT_0V_0S_0} \right]$ (3.41)

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(2)

.(0.0002= / 1

$\Delta t \geq 1.625 \mu / V_w$
 $2.6 \mu / V_w \leq \Delta L \leq 1.6 V_w \Delta t$
 $\mu = \frac{Q_0}{2WS}$

$.m^2/sec \qquad \qquad \qquad : \mu$
 $.m^3/s \qquad \qquad \qquad :Q0$
 $.m \qquad \qquad \qquad :W$
 $\qquad \qquad \qquad . \qquad \qquad \qquad :S$
 $\qquad \qquad \qquad : \qquad \qquad \qquad - \quad -$
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		$S_f = S_0 - \frac{dy}{dx} - \frac{v}{g} \frac{dv}{dx} - \frac{1}{g} \frac{dv}{dt}$
جريان منتظم دائم		
تقريبات الموجة الحركية		
جريان غير منتظم دائم		
تقريبات الموجة المشتتة		
جريان غير منتظم دائم		
تقريبات الموجة الديناميكية الشبه دائمة		
جريان غير منتظم غير دائم		
تقريبات الموجة الديناميكية الكاملة		

:-

$S_f = S_0$

:

$\frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = 0$ (3.42)

:

$S_f = S_0$ (3.43)

:

$\frac{\partial Q}{\partial t} + C \frac{\partial Q}{\partial x} = 0$ (3.44)

$$\frac{c}{x} \frac{dt}{Q} = \frac{c}{x} \frac{dx}{c} = \frac{dx}{x} = \frac{1}{x} dx$$

$$\frac{T_r S_0 V_0}{d_0} \geq 85 \tag{3.45}$$

$$O_2 = C_0 I_2 + C_1 I_1 + C_2 O_2 \tag{3.46}$$

$$C_0 = \frac{C-1}{1+C} \tag{3.47}$$

$$C1=1 \tag{3.48}$$

$$C_2 = \frac{1-C}{1+C} \tag{3.49}$$

$$C=c\frac{\Delta t}{\Delta x} \tag{3.50}$$

$$c = (5/3)V \quad \text{B} \quad (dQ/dy)/B \quad \text{C} \quad dQ/dy \quad Q \quad y \quad \text{.Courant} \quad \text{C} \quad \Delta x, \Delta t$$

$$\frac{5}{3} V \quad c \quad \Delta x \quad - \quad - \quad \Delta t \quad - \quad -$$

$$Q = \alpha A^m \tag{3.51}$$

α, m

$$\frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = 0 \tag{3.52}$$

$$\frac{\partial A}{\partial t} + \alpha m A^{(m-1)} \frac{\partial A}{\partial x} = 0 \tag{3.53}$$

$$(0.002 = \quad / \quad 10)$$

$$.(\quad \dots \quad)$$

: (Atti-kin) - - - -

Atti-kin

$$I_1 - \frac{O_2 - O_1}{2} = \frac{S_2 - S_1}{\Delta t} \quad (3.54)$$

$$O_2 = C_m I_1 + (1 - C_m) O_1 \quad (3.55)$$

$$C_m = \frac{2\Delta t}{2k + \Delta t} \quad (3.56)$$

$$Q = XA^m.$$

$$x = \frac{S_0^{1/2}}{np^{2/3}} \quad (3.57)$$

$$\Delta tp = \frac{Op(1/m-1)}{X^{1/m}} L\left(\frac{(Ip/Op)^{1/m}-1}{(Ip/Op)-1}\right) \quad (3.58)$$

. Op Ip

	:	-
.	x,m	-
$\cdot (Cm \leq 0.67 \quad) \; 1 \quad \text{Cm}$	$\cdot \Delta t \quad \text{Cm,K}$	-
	.	-
$\cdot \Delta t_{ps}$	$\cdot \Delta t_p$	-
$\Delta t_p - \Delta t_{ps}$	$\Delta t_p \leq \Delta t_{ps}$	-
	.	

	:	- - - -
$S_f = S_0 - \frac{dy}{dx}$		(3.59)
.	(\quad)	
	:	-

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$$S_f = S_0 - \left(\frac{dy}{dx}\right) - \left(\frac{v dv}{g dx}\right)$$

(3.60)

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$$\frac{QR-QP}{\Delta X} + BP \frac{yM-yP}{\Delta t} + \sqrt{\frac{BP}{g.AP}} \left[\begin{aligned} & \frac{QM-QP}{\Delta t} + 2 \frac{QP}{AP} \frac{QR-QP}{\Delta X} \\ & + (gAP - \frac{QP^2}{AP^2} BP) (\frac{yR-yP}{\Delta X} - S0) \\ & - \frac{QP^2}{AP^2} \frac{AR-APR}{\Delta X} + g \frac{QP|P|}{APMP^2 RP^{4/3}} \end{aligned} \right] = 0 \quad (3.61)$$

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$$\frac{QP-QL}{\Delta X} + BP \frac{yM-yP}{\Delta t} + \sqrt{\frac{BP}{g.AP}} \left[\begin{aligned} & \frac{QM-QP}{\Delta t} + 2 \frac{QP}{AP} \frac{QP-QL}{\Delta X} + \\ & (gAP - \frac{QP^2}{AP^2} BP) (\frac{yP-yL}{\Delta X} - S0) \\ & - \frac{QP^2}{AP^2} \frac{APL-AL}{\Delta X} + g \frac{QP|P|}{APMP^2 RP^{4/3}} \end{aligned} \right] = 0 \quad (3.62)$$

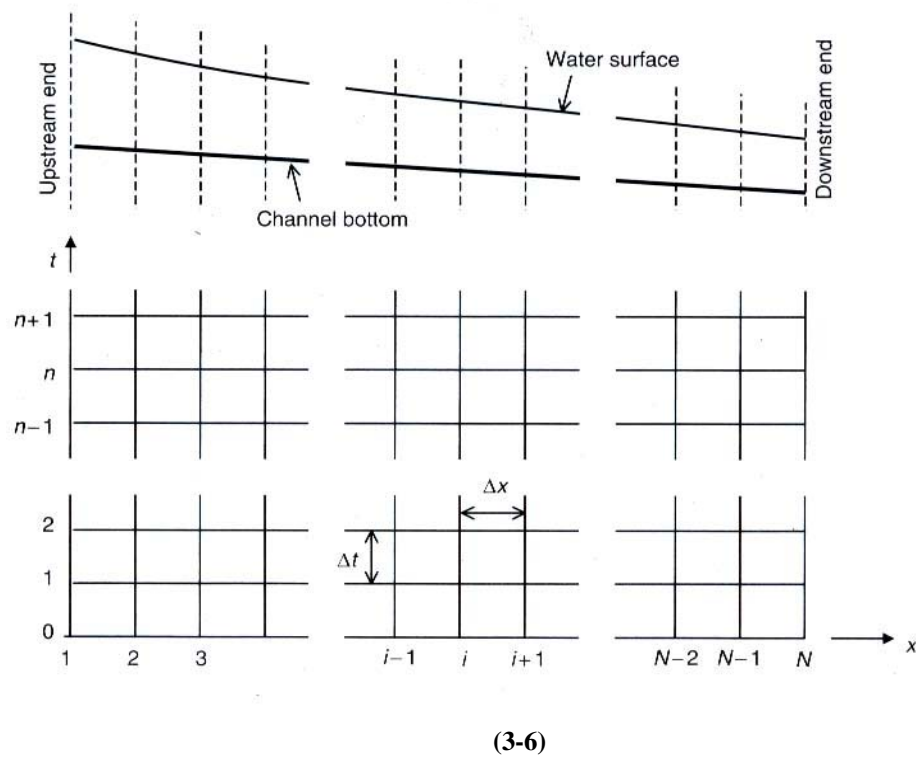
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$$QM = QP + \frac{\Delta t}{2 \Delta x} \left[\begin{aligned} & \sqrt{g \frac{AP}{BP}} (QL - 2 QP + QR) - \\ & 2 \frac{QP}{AP} (QR - QL) - \\ & ((yR - yL) - 2 S0 \Delta X / \Delta t) (g.AP - \frac{QP^2}{AP^2} BP) \\ & + \frac{QP^2}{AP^2} (AR - ABR + ABL - AL) \end{aligned} \right]$$

(3.63)

$$yM = yP + \frac{\Delta t}{2BP\Delta X} \left[\begin{aligned} &QL - QR - \sqrt{\frac{BP}{gAP}} \left(2 \frac{QP}{gAP} - QR - QL \right) - \\ &(yR - 2yP + yL) \left(gAP - \frac{QP^2}{AP^2} BP \right) \\ &+ \frac{QP^2}{AP^2} (AR - APR - APL + AL) \end{aligned} \right] \quad (3.64)$$

$$\Delta t \leq \frac{\Delta x}{\frac{Q}{A} + \sqrt{g A/B}} \quad (3.65)$$


$$\begin{array}{ccc}
 n & & n+1 \\
 1,2 & & \\
 & & \\
 n+1 & & n \\
 y_i^{n+1}, Q_i^{n+1} & i=1,2,3,\dots N & y_i^n, Q_i^n \\
 .y,Q & A,Sf & i=1,2,3,\dots N
 \end{array}$$

$$\frac{\partial f}{\partial x} = \frac{f_{i+1}^j - f_i^j}{\Delta x} \quad (3.66)$$

$$\frac{\partial f}{\partial t} = \frac{f_i^{j+1} - f_i^j}{\Delta t} \quad (3.67)$$

•

$$\frac{Q_{i+1}^j-Q_i^j}{\Delta x}+\frac{A_i^{j+1}-A_i^j}{\Delta t}=0 \tag{3.68}$$

:

$$\frac{Q_i^{j+1}-Q_i^j}{\Delta t}+\frac{(Q^2/A)_{i+1}^j-(Q^2/A)_i^j}{\Delta x}+gA(\frac{h_i^{j+1}-h_i^j}{\Delta x}+sf) \tag{3.69}$$

:

(courant)

$$\Delta t \leq \frac{\Delta x}{|V \mp C|} \tag{3.70}$$

:(koren)

$$\Delta t \leq \frac{\sqrt{1+2F_0}-1}{F_0\frac{gS_0}{V_0}} \tag{3.71}$$

:

:F0

:V0

:S0

(Sign, Hung)

(Koren)

(courant)

(koren)

(courant)

$$\Delta x_{\max}=(\sqrt{1+2Fr_0}-1)(1+Fr_0)\frac{y_0}{S_0}$$

(3.72)

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:

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n+1

n

. n+1

. n+1 ()

. N-1

:2N

.i=1,2,3,...N

2N-2

2N

.(preissman)

i , (preissman) :i+1

$$\frac{\partial A}{\partial t} \approx \frac{(A_{i+1}^{n+1} - A_i^{n+1}) - (A_{i+1}^n - A_i^n)}{2\Delta t} \quad (3.73)$$

$$\frac{\partial Q}{\partial t} \approx \frac{(Q_{i+1}^{n+1} - Q_i^{n+1}) - (Q_{i+1}^n - Q_i^n)}{2\Delta t} \quad (3.74)$$

$$\frac{\partial Q}{\partial x} \approx \frac{\theta(Q_{i+1}^{n+1} - Q_i^{n+1}) + (1-\theta)(Q_{i+1}^n - Q_i^n)}{\Delta x} \quad (3.75)$$

$$\frac{\partial(Q^2/A)}{\partial x} \approx \frac{\theta\{[Q^2/A]_{i+1}^{n+1} - [Q^2/A]_i^{n+1}\}}{\Delta x} + \frac{(1-\theta)\{[Q^2/A]_{i+1}^n - [Q^2/A]_i^n\}}{\Delta x} \quad (3.76)$$

$$A \frac{\partial h}{\partial x} \approx \theta \frac{(A_{i+1}^{n+1} + A_i^{n+1})}{2} \frac{(h_{i+1}^{n+1} - h_i^{n+1})}{\Delta x} + (1-\theta) \frac{(A_{i+1}^n + A_i^n)}{2} \frac{(h_{i+1}^n - h_i^n)}{\Delta x} \quad (3.77)$$

$$A \approx \theta \frac{(A_{i+1}^{n+1} + A_i^{n+1})}{2} + (1-\theta) \frac{(A_{i+1}^n + A_i^n)}{2} \quad (3.78)$$

$$AS_F \approx \theta \frac{(A_{i+1}^{n+1} + A_i^{n+1})}{2} \frac{(S_{f_{i+1}}^{n+1} - S_{f_i}^{n+1})}{\Delta x} + (1-\theta) \frac{(A_{i+1}^n + A_i^n)}{2} \frac{(S_{f_{i+1}}^n - S_{f_i}^n)}{\Delta x} \quad (3.79)$$

$\theta=1$

(0-1) θ

$\theta=0.5$

0 θ

$0.5 \leq \theta \leq 1$

$$(3.75),(3.73) \hspace{100pt} \theta=0.55$$

$$:$$

$$(3.2)$$

$$\frac{(A_{i+1}^{n+1}-A_i^{n+1})-(A_{i+1}^n-A_i^n)}{2\Delta t}+\frac{\theta(Q_{i+1}^{n+1}-Q_i^{n+1})+(1-\theta)(Q_{i+1}^n-Q_i^n)}{\Delta x}=0 \hspace{10pt} (3.80)$$

$$\frac{(Q_{i+1}^n+Q_i^{n+1})-(Q_{i+1}^n-Q_i^n)}{2\Delta t}\frac{\partial(Q^2/A)}{\partial x}\approx$$

$$\frac{\theta\left\{[Q^2/A]_{i+1}^{n+1}-[Q^2/A]_i^{n+1}\right\}}{\Delta x}+\frac{(1-\theta)\left\{[Q^2/A]_{i+1}^n-[Q^2/A]_i^n\right\}}{\Delta x}+$$

$$g\theta\frac{(A_{i+1}^{n+1}+A_i^{n+1})}{2}\frac{(S_{f\,i+1}^{n+1}+S_{f\,i}^{n+1})}{2}$$

$$+g(1-\theta)\frac{(A_{i+1}^{n+1}+A_i^n)}{2}\frac{(S_{f\,i+1}^{n+1}+S_{f\,i}^{n+1})}{2}=0 \hspace{10pt} (3.81)$$

$$:$$

$$Q_i^{n+1}-Q_{up}^{n+1}=0 \hspace{10pt} (3.82)$$

$$.n+1 \hspace{100pt} Q_{up}^{n+1}$$

$$:$$

$$(Fr=1)$$

$$\frac{Q_N^{n+1}(T_N^{n+1})^{1/2}}{\sqrt{g}(A_N^{n+1})^{3/2}}-1=0 \hspace{10pt} (3.83)$$

$$:$$

$$:$$

$$:$$

$$S_{f\,N}^{n+1}-S_0=0 \hspace{10pt} (3.84)$$

$$:$$

$$:S0$$

$$y_N,Q_N,A_N$$

$$.n1$$

$$:-$$

$$i=1,2,3,...N \hspace{10pt} Q_i^{n+1},h_i^{n+1}$$

$$Q_i^{n+1},h_i^{n+1} \hspace{10pt} S_{f\,i}^{n+1}$$

$$C_i[Q_i^{n+1}, h_i^{n+1}, Q_{i+1}^{n+1}, h_{i+1}^{n+1}] = 0 \quad (3.85)$$

$$M_i[Q_i^{n+1}, h_i^{n+1}, Q_{i+1}^{n+1}, h_{i+1}^{n+1}] = 0 \quad (3.86)$$

Mi,Ci

i,i+1

(3.86),(3.85)

.BN

B1

2N

(N-1)

i=1

:

2N

$$B_1[Q_1^{n+1}, h_1^{n+1}] = 0$$

$$C_1[Q_1^{n+1}, h_1^{n+1}, Q_2^{n+1}, h_2^{n+1}] = 0$$

$$M_1[Q_1^{n+1}, h_1^{n+1}, Q_2^{n+1}, h_2^{n+1}] = 0$$

$$C_2[Q_2^{n+1}, h_2^{n+1}, Q_3^{n+1}, h_3^{n+1}] = 0$$

$$M_2[Q_2^{n+1}, h_2^{n+1}, Q_3^{n+1}, h_3^{n+1}] = 0 \quad (3.87)$$

$$C_i[Q_i^{n+1}, h_i^{n+1}, Q_{i+1}^{n+1}, h_{i+1}^{n+1}] = 0$$

$$M_i[Q_i^{n+1}, h_i^{n+1}, Q_{i+1}^{n+1}, h_{i+1}^{n+1}] = 0$$

$$C_{N-1}[Q_{N-1}^{n+1}, h_{N-1}^{n+1}, Q_N^{n+1}, h_N^{n+1}] = 0$$

$$M_{N-1}[Q_{N-1}^{n+1}, h_{N-1}^{n+1}, Q_N^{n+1}, h_N^{n+1}] = 0$$

$$B_N[Q_N^{n+1}, h_N^{n+1}] = 0$$

.i=1,2,3,...N

2N

2N

$$Q_i^{n+1}, h_i^{n+1}$$

(3.87)

i=1,2,3,...N

.rB1,rC1,rM1,rC2,rM2,rCi,rMi,...,rBn-1,rMN-1,rCN-1,rBN

i=1,2,3,...N

$$Q_i^{n+1}, h_i^{n+1}$$

.

$$\Delta Q_i, \Delta h_i$$

.

$$\begin{array}{c}
i=1,2,3,\dots,N \quad \Delta Q_i^{n+1}, \Delta h_i^{n+1} \\
B1, C1, M1, C2, M2, C_i, M_i, \dots, B_{n-1}, M_{n-1}, C_{n-1}, B_N \\
: \\
\frac{\partial B}{\partial Q_1^{n+1}} \Delta Q_1 + \frac{\partial B}{\partial h_1^{n+1}} \Delta h_1 = -rB \\
\frac{\partial C_1}{\partial Q_1^{n+1}} \Delta Q_1 + \frac{\partial C_1}{\partial h_1^{n+1}} \Delta h_1 + \frac{\partial C_1}{\partial Q_2^{n+1}} \Delta Q_2 + \frac{\partial C_1}{\partial h_2} \Delta h_2 = -rC_1 \\
\frac{\partial M_1}{\partial Q_1^{n+1}} \Delta Q_1 + \frac{\partial M_1}{\partial h_1^{n+1}} \Delta h_1 + \frac{\partial M_1}{\partial Q_2^{n+1}} \Delta Q_2 + \frac{\partial M_1}{\partial h_2} \Delta h_2 = -rM_1 \\
\frac{\partial C_2}{\partial Q_2^{n+1}} \Delta Q_2 + \frac{\partial C_2}{\partial h_2^{n+1}} \Delta h_2 + \frac{\partial C_2}{\partial Q_3^{n+1}} \Delta Q_3 + \frac{\partial C_2}{\partial h_3} \Delta h_3 = -rC_2 \\
\frac{\partial M_2}{\partial Q_2^{n+1}} \Delta Q_2 + \frac{\partial M_2}{\partial h_2^{n+1}} \Delta h_2 + \frac{\partial M_2}{\partial Q_3^{n+1}} \Delta Q_3 + \frac{\partial M_2}{\partial h_3} \Delta h_3 = -rM_2 \\
\frac{\partial C_i}{\partial Q_i^{n+1}} \Delta Q_i + \frac{\partial C_i}{\partial h_i^{n+1}} \Delta h_i + \frac{\partial C_i}{\partial Q_{i+1}^{n+1}} \Delta Q_{i+1} + \frac{\partial C_i}{\partial h_{i+1}} \Delta h_{i+1} = -rC_i \\
\frac{\partial M_i}{\partial Q_i^{n+1}} \Delta Q_i + \frac{\partial M_i}{\partial h_i^{n+1}} \Delta h_i + \frac{\partial M_i}{\partial Q_{i+1}^{n+1}} \Delta Q_{i+1} + \frac{\partial M_i}{\partial h_{i+1}} \Delta h_{i+1} = -rM_i \\
\text{.....} \\
\text{.....} \\
\frac{\partial C_{N-1}}{\partial Q_{N-1}^{n+1}} \Delta Q_{N-1} + \frac{\partial C_{N-1}}{\partial h_{N-1}^{n+1}} \Delta h_{N-1} + \frac{\partial C_{N-1}}{\partial Q_N^{n+1}} \Delta Q_N + \frac{\partial C_{N-1}}{\partial h_N} \Delta h_N = -rC_{N-1} \\
\frac{\partial M_{N-1}}{\partial Q_{N-1}^{n+1}} \Delta Q_{N-1} + \frac{\partial M_{N-1}}{\partial h_{N-1}^{n+1}} \Delta h_{N-1} + \frac{\partial M_{N-1}}{\partial Q_N^{n+1}} \Delta Q_N + \frac{\partial M_{N-1}}{\partial h_N} \Delta h_N = -rM_{N-1} \\
\frac{\partial B_N}{\partial Q_N^{n+1}} \Delta Q_N + \frac{\partial B_N}{\partial h_N^{n+1}} \Delta h_N = -rB_N \\
2N \quad 2N \\
i=1,2,3,\dots,N \quad \Delta Q_i, \Delta h_i \\
n+1 \\
:
\end{array} \tag{3.88}$$

$$\left[\begin{array}{cccccccccc} \frac{\partial B_1}{\partial Q_1} & \frac{\partial B_1}{\partial C_1} & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{\partial Q_1}{\partial C_1} & \frac{\partial h_1}{\partial C_1} & \frac{\partial C_1}{\partial Q_2} & \frac{\partial C_2}{\partial h_2} & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{\partial M_1}{\partial Q_1} & \frac{\partial M_1}{\partial h_1} & \frac{\partial M_1}{\partial Q_2} & \frac{\partial M_2}{\partial h_2} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{\partial C_2}{\partial Q_2} & \frac{\partial C_2}{\partial h_2} & \frac{\partial C_3}{\partial Q_3} & \frac{\partial C_3}{\partial h_3} & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{\partial M_2}{\partial Q_2} & \frac{\partial M_2}{\partial h_2} & \frac{\partial M_3}{\partial Q_3} & \frac{\partial M_3}{\partial h_3} & 0 & 0 & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & 0 & 0 & 0 & 0 & \frac{\partial \dot{C}_{N-1}}{\partial Q_{N-1}} & \frac{\partial \dot{C}_{N-1}}{\partial h_{N-1}} & \frac{\partial \dot{C}_N}{\partial Q_N} & \frac{\partial \dot{C}_N}{\partial h_N} \\ 0 & 0 & 0 & 0 & 0 & 0 & \frac{\partial \dot{M}_{N-1}}{\partial Q_{N-1}} & \frac{\partial \dot{M}_{N-1}}{\partial h_{N-1}} & \frac{\partial \dot{M}_N}{\partial Q_N} & \frac{\partial \dot{M}_N}{\partial h_N} \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \frac{\partial B_N}{\partial Q_N} & \frac{\partial B_N}{\partial h_N} \end{array} \right]^* \quad (3.89)$$

$$\begin{bmatrix} \Delta Q_1 \\ \Delta h_1 \\ \Delta Q_2 \\ \Delta h_2 \\ \Delta Q_3 \\ \Delta h \\ . \\ . \\ . \\ \Delta Q_N \\ \Delta h_N \end{bmatrix} = \begin{bmatrix} -rB_1 \\ -rC_1 \\ -rM_1 \\ -rC_2 \\ -rM_2 \\ . \\ . \\ . \\ -rC_{N-1} \\ -rM_{N-1} \\ -rB_N \end{bmatrix}$$

(Gaussian)

$$\begin{aligned} & \vdots \quad \mathcal{Q}_i^{n+1}, h_i^{n+1} \\ (\mathcal{Q}_i^{n+1})_{K+1} &= (\mathcal{Q}_i^{n+1})_K + (\Delta \mathcal{Q}_i)_K \end{aligned} \quad (3.90)$$

$$(h_i^{n+1})_{K+1} = (h_i^{n+1})_K + (\Delta h_i)_K \quad (3.91)$$

$$\begin{aligned} & \cdot \qquad \qquad \qquad \text{k,k+1} \\ & \cdot \\ & \cdot \\ & \qquad \qquad \qquad \vdots \qquad \qquad \qquad - \\ & \qquad \qquad \qquad (3.89) \\ (3.80) \qquad \qquad \qquad) \end{aligned}$$

$$(3.84)$$

$$\begin{aligned} & \text{n+1} \\ & \qquad \qquad \qquad \vdots \\ \frac{\partial B_1}{\partial Q_1} &= 1 \qquad \qquad \qquad (3.92) \\ \frac{\partial B_1}{\partial h_1} &= 0 \qquad \qquad \qquad (3.93) \end{aligned}$$

$$.(3.84)$$

$$\begin{aligned} & \qquad \qquad \qquad \vdots \qquad \text{Sf} \\ S_f &= \frac{n^2 P^{4/3} Q |Q|}{K_n^2 A^{10/3}} \qquad \qquad \qquad (3.94) \\ & \qquad \qquad \qquad \vdots \\ \frac{\partial B_N}{\partial Q_N} &= \frac{\partial S_{f_N}}{\partial Q_N} = \frac{2n^2 P_N^{4/3} |Q_N|}{K_n^2 A_N^{10/3}} \qquad \qquad \qquad (3.95) \\ \frac{\partial B_N}{\partial h_N} &= \frac{\partial S_{f_N}}{\partial h_N} = \frac{n^2 Q_N |Q_N|}{K_n^2 A_N^{20/3}} (\frac{4}{3} P_N^{1/3} \frac{\partial P_N}{\partial h_N} A_N^{10/3} - \frac{10}{3} A_N^{7/3} \frac{\partial A_N}{\partial h_N} P_N^{4/3}) \qquad (3.96) \end{aligned}$$

$$\begin{aligned} & \cdot \qquad \qquad \qquad \partial A / \partial h \quad \partial P / \partial h \\ & \qquad \qquad \qquad \text{i+1} \quad \text{i} \qquad \qquad \qquad (3.80) \end{aligned}$$

$$\cdot \qquad \qquad \qquad \text{n+1}$$

$$\begin{aligned} & \qquad \qquad \qquad \vdots \\ \frac{\partial C_i}{\partial Q_i} &= - \frac{\theta}{\Delta x} \qquad \qquad \qquad (3.97) \\ \frac{\partial C_i}{\partial h_i} &= \frac{1}{2 \Delta t} \frac{\partial A_i}{\partial h_i} \qquad \qquad \qquad (3.98) \end{aligned}$$

$$\frac{\partial C_i}{\partial Q_{i+1}} = \frac{\theta}{\Delta x} \quad (3.99)$$

$$\frac{\partial C_i}{\partial h_{i+1}} = \frac{1}{2\Delta t} \frac{\partial A_{i+1}}{\partial h_{i+1}} \quad (3.100)$$

$$n+1 \quad i+1 \quad i \quad (3.81)$$

$$: \quad (3.81)$$

$$\frac{\partial M_i}{\partial Q_i} = \frac{1}{2\Delta t} - \frac{2\theta Q_i}{A_i \Delta x} + g\theta \frac{(A_{i+1} + A_i)}{4} \frac{\partial S_{f_i}}{\partial Q_i} \quad (3.101)$$

$$\frac{\partial M_i}{\partial h_i} = \frac{\theta}{\Delta x} \frac{Q_i^2}{A_i^2} \frac{\partial A_i}{\partial h_i} - g\theta \frac{(A_{i+1} + A_i)}{2\Delta x} \quad (3.102)$$

$$+ g\theta \frac{(h_{i+1} - h_i)}{2\Delta x} \frac{\partial A_i}{\partial h_i} + g\theta \frac{S_{f_{i+1}} + S_{f_i}}{4} \frac{\partial A_i}{\partial h_i} + g\theta \frac{(A_{i+1} + A_i)}{4} \frac{\partial S_{f_i}}{\partial h_i}$$

$$\frac{\partial M_i}{\partial Q_{i+1}} = \frac{1}{2\Delta t} + \frac{2\theta Q_{i+1}}{A_i \Delta x} + g\theta \frac{(A_{i+1} + A_i)}{4} \frac{\partial S_{f_{i+1}}}{\partial Q_{i+1}} \quad (3.103)$$

$$\frac{\partial M_i}{\partial h_{i+1}} = -\frac{\theta}{\Delta x} \frac{Q_{i+1}^2}{A_{i+1}^2} \frac{\partial A_{i+1}}{\partial h_{i+1}} + g\theta \frac{(A_{i+1} + A_i)}{2\Delta x} + g\theta \frac{(h_{i+1} - h_i)}{2\Delta x} \frac{\partial A_{i+1}}{\partial h_{i+1}} + g\theta \frac{S_{f_{i+1}} + S_{f_i}}{4} \frac{\partial A_{i+1}}{\partial h_{i+1}} +$$

$$g\theta \frac{(A_{i+1} + A_i)}{4} \frac{\partial S_{f_{i+1}}}{\partial h_{i+1}}$$

$$(3.104)$$

$$\text{Sf} \quad (3.94)$$

:

$$\frac{\partial S_{f_i}}{\partial Q_i} = \frac{2n^2 P_i^{4/3} |Q_i|}{K_n^2 A_i^{10/3}} \quad (3.105)$$

$$\frac{\partial S_{f_i}}{\partial h_i} = \frac{n^2 Q_i |Q_i|}{K_n^2 A_i^{20/3}} \left(\frac{4}{3} P_i^{1/3} \frac{\partial P_i}{\partial h_i} A_i^{10/3} - \frac{10}{3} A_i^{7/3} \frac{\partial A_i}{\partial h_i} P_i^{4/3} \right) \quad (3.106)$$

$$\partial A / \partial h \quad \partial P / \partial h$$

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$$\Delta t \quad \Delta x$$

$$. \Delta t \quad \Delta x$$

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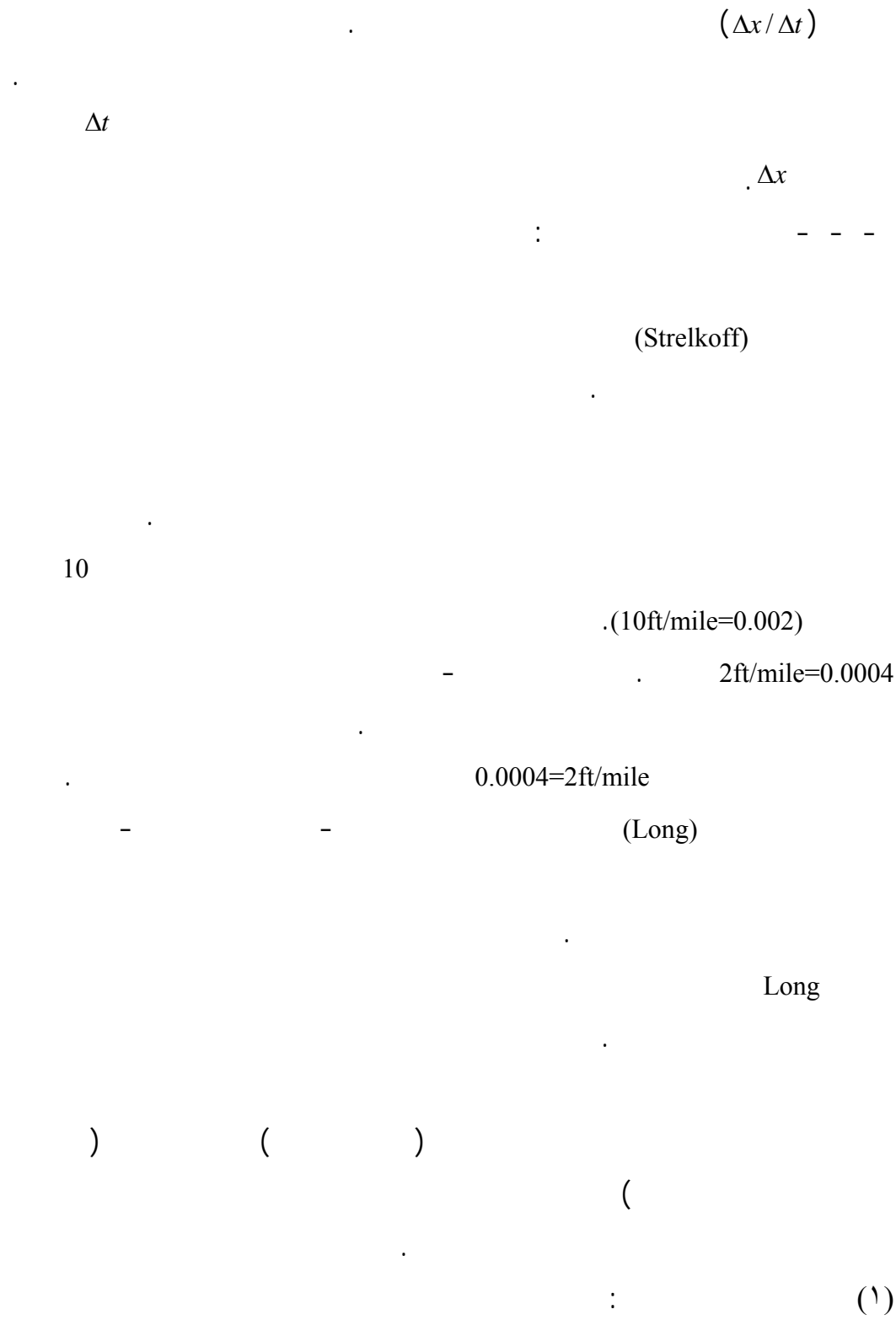
courant

$$\Delta x / \Delta t$$

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courant

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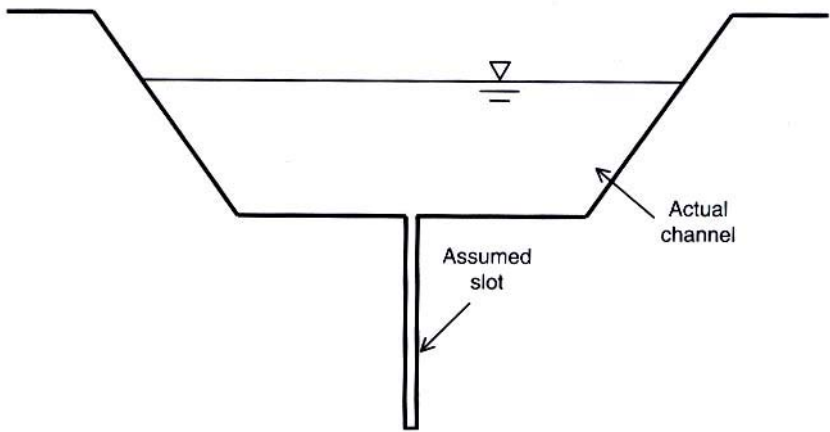
(3-2)

-	- - - -	-
-	- - -	- - -
-	-	-
-	-	-
$\begin{array}{l} : 0.002 < \\ \frac{T S_0 U_0}{d_0} \geq 171 \end{array}$	-	-
$\begin{array}{l} 0.002 \\ : 0.0004 \\ \frac{T S_0 U_0}{d_0} < 171 \end{array}$	- - -	-
$\begin{array}{l} : 0.0004 > \\ T S_0 (\frac{g}{d_0})^{1/2} \geq 30 \end{array}$	- - -	- -
$\begin{array}{l} : 0.0004 > \\ T S_0 (\frac{g}{d_0})^{1/2} < 30 \end{array}$	-	-

: - - -

(3-7) ()

(Currey)



(3-7)

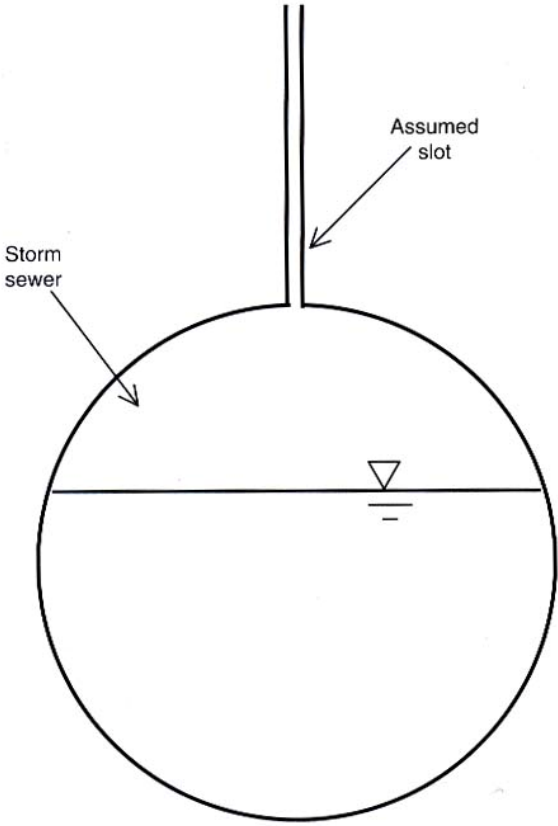
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(3.8)

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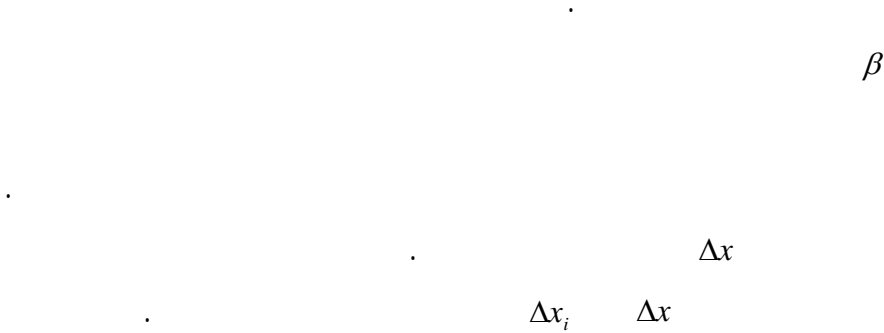
(Preissmann)

(3-8)

((3.11)

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β



الفصل الرابع

تأثير التدفقات الفرعية في التدفقات الرئيسية

$$q_l = \frac{Q_l}{b_l} \tag{4.1}$$

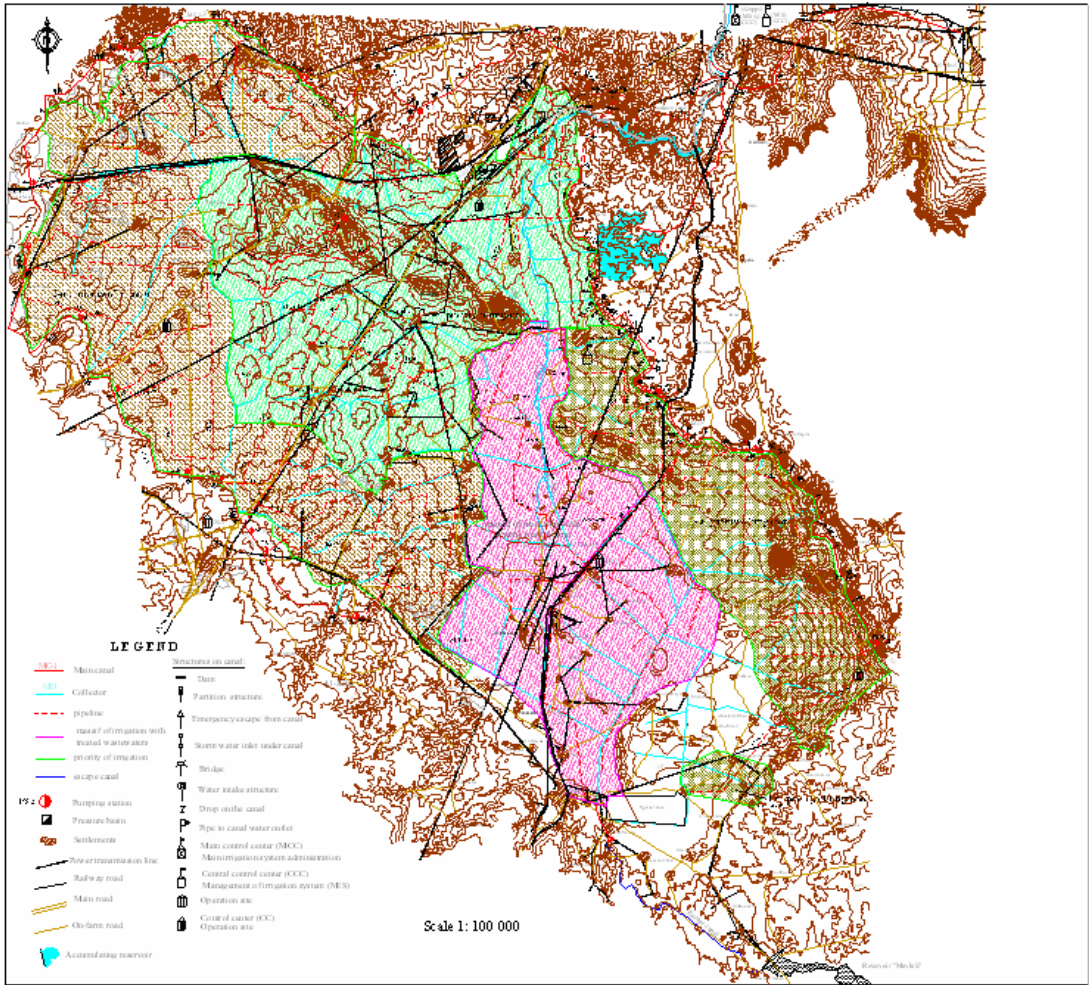
$$u_l = \frac{Q_l}{A_l} \cos \alpha \tag{4.2}$$

	:
$. m^3 / s$: Q_l
$. m$: b_l
$. m^2$: A_l
	: θ
:	-

الفصل الخامس

منطقة الدراسة

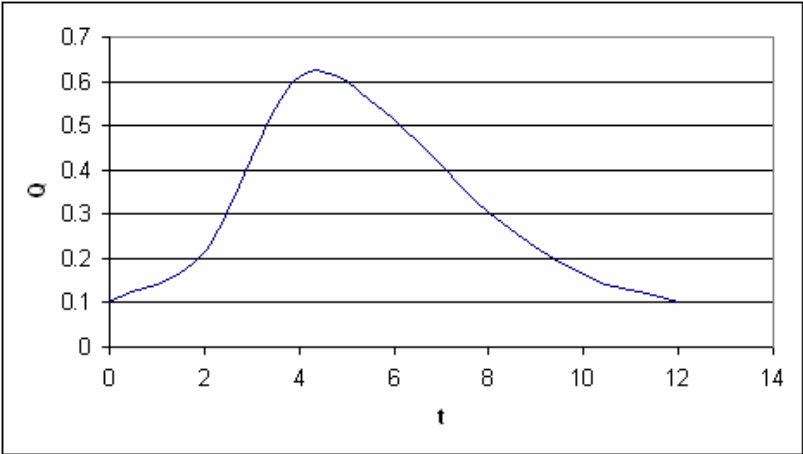
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		25	-
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		15	-
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()	-١	
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36.5	6	MC-S:	-
68		343	1
		.MC-S	
12100		-	
		.	
		-	



(5-1)

ML-2

16D	14D,16D	MD			
MD	14D	60	3662		MD
			60	8400	
					:



16D

(5-3)

:14D -

0.0006 1.5 2.5m

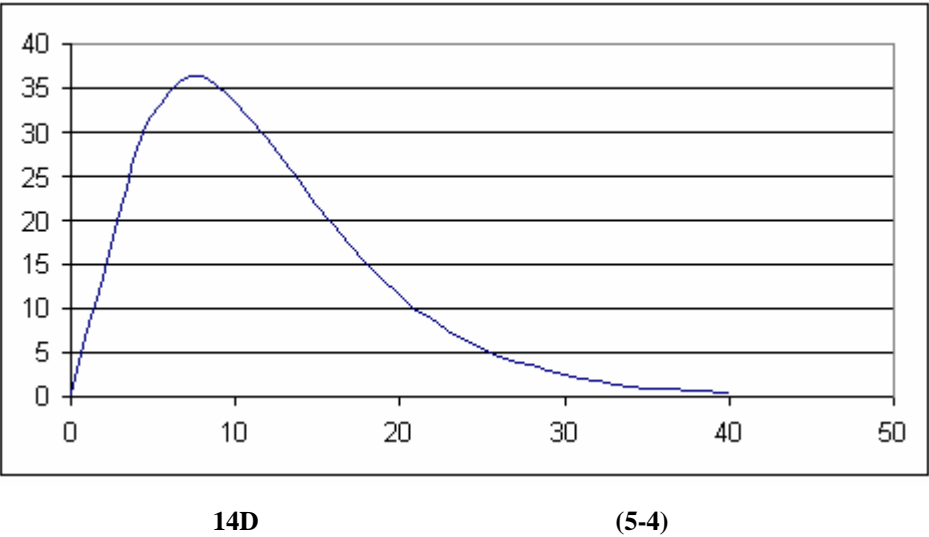
2 0.03

: 2850m 21

14D

(5-3)

t	Q
0	0.15
2	13.43
4	27.44
6	34.61
8	36.27
10	33.39
12	29.23
14	24.37
16	19.50
18	15.23
20	11.62
22	8.67
24	6.34
26	4.61
28	3.45
30	2.47
32	1.77
34	1.06
36	0.91
38	0.76
40	0.46



0.00075

2

1.5

2.5m

0.03

10200m

: MD

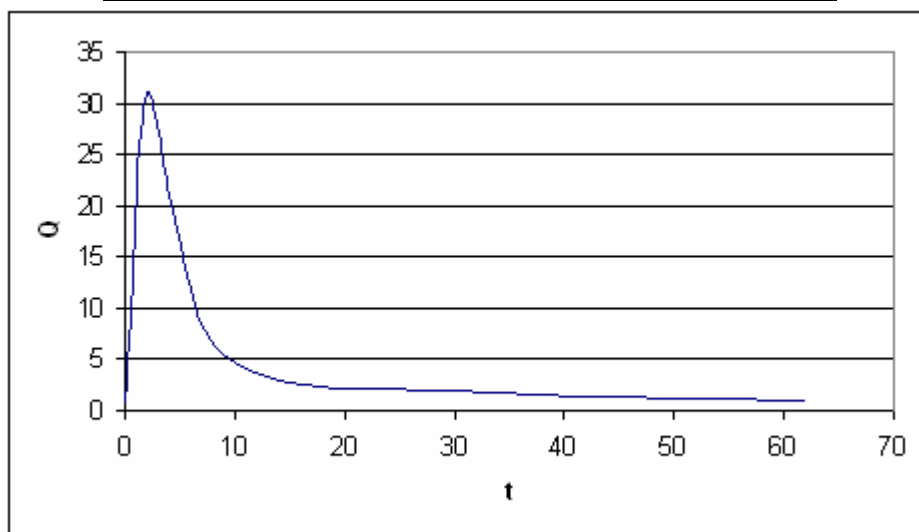
-

32

MD (5-4)

t(hr)	Q
0	0.81
2	30.24
4	21
6	11.87
8	6.81
10	4.68
12	3.52
14	2.88
16	2.43
18	2.23
20	2.1
22	2.05
24	1.99
26	1.93
28	1.88
30	1.81
32	1.71
34	1.61

36	1.54
38	1.44
40	1.34
42	1.31
44	1.27
46	1.23
48	1.195
50	1.16
52	1.12
54	1.08
56	1.05
58	1.02
60	0.997
62	0.97



MD

(5-5)

الفصل السادس

طريقة البحث

: - -

Kiskin

Remando

Q

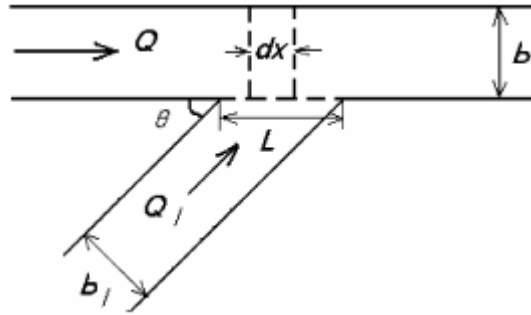
(6-1)

S_0

b

b_l

Q_l



(6-1)

$$\frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = q_l \quad (6.1)$$

$$\frac{\partial Q}{\partial t} + \frac{\partial}{\partial x} \left(\frac{Q^2}{A} \right) = -gA \left(\frac{\partial h}{\partial x} - S_0 + S_f \right) + q_l u_l \quad (6.2)$$

$$u_l = \frac{Q_l}{A_l} \cos \theta \quad (6.3)$$

$$q_l = \frac{Q_l}{B_l} \quad (6.4)$$

:

$$\frac{\partial Q}{\partial t} + \frac{\partial}{\partial x} \left(\frac{Q^2}{A} \right) + gA \left(\frac{\partial h}{\partial x} - S_0 \right) + gAS_f = q_l u_l \quad (6.5)$$

:

$$A = (b + mh)h = b + mh^2 \Rightarrow \frac{\partial A}{\partial x} = b \frac{\partial h}{\partial x} + 2mh \frac{\partial h}{\partial x} \quad (6.6)$$

$$\frac{\partial h}{\partial x} = \frac{1}{b+2mh} \frac{\partial A}{\partial x} = \frac{1}{B} \frac{\partial A}{\partial x} \quad (6.7)$$

:

$$\begin{aligned} \frac{\partial Q}{\partial t} + \frac{2Q}{A} \frac{\partial Q}{\partial x} - \frac{Q^2}{A^2} \frac{\partial A}{\partial x} + gA \left(\frac{1}{B} \frac{\partial A}{\partial x} - S_0 \right) + gAS_f &= q_l u_l \\ \frac{\partial Q}{\partial t} + \frac{2Q}{A} \frac{\partial Q}{\partial x} + \left(-\frac{Q^2}{A^2} + \frac{gA}{B} \right) \frac{\partial A}{\partial x} - gAS_0 + gAS_f &= q_l u_l \\ \frac{\partial Q}{\partial t} + \frac{2Q}{A} \frac{\partial Q}{\partial x} + \left(\frac{gA}{B} - \frac{Q^2}{A^2} \right) \frac{\partial A}{\partial x} + gA(S_f - S_0) &= q_l u_l \end{aligned} \quad (6.8)$$

$$V = \frac{1}{n} R^{2/3} S_f^{1/2} :$$

$$R = A/P :$$

$$P = b + 2h\sqrt{1+m^2} :$$

:

$$\frac{\partial P}{\partial x} = 2\sqrt{1+m^2} \frac{\partial h}{\partial x}$$

:

$$\begin{aligned} \frac{\partial R}{\partial x} &= \frac{1}{P} \left(\frac{\partial A}{\partial x} - \frac{R \partial P}{\partial x} \right) = \frac{1}{P} \left(\frac{\partial A}{\partial x} - 2R\sqrt{1+m^2} \frac{\partial h}{\partial x} \right) \\ &= \frac{1}{P} \left(\frac{\partial A}{\partial x} - 2R\sqrt{1+m^2} \frac{1}{B} \frac{\partial A}{\partial x} \right) = \frac{1}{P} \left(1 - 2R \frac{\sqrt{1+m^2}}{B} \right) \frac{\partial A}{\partial x} \\ \frac{\partial R}{\partial x} &= \frac{1}{P} \left(1 - 2R \frac{\sqrt{1+m^2}}{B} \right) \frac{\partial A}{\partial x} \end{aligned} \quad (6.9)$$

:

$$\frac{\partial Q}{\partial x} = \frac{2}{3} \frac{1}{n} R^{-1/3} S_f^{1/2} \left[\frac{1}{P} \left(1 - 2R \frac{\sqrt{1+m^2}}{B} \right) \frac{\partial A}{\partial x} \right] A + V \frac{\partial A}{\partial x} \quad (6.10)$$

:

$$\begin{aligned} \frac{\partial Q}{\partial x} &= \left(\frac{2}{3} \frac{1}{n} R^{-1/3} S_f^{1/2} \left[\frac{1}{P} \left(1 - 2R \frac{\sqrt{1+m^2}}{B} \right) \right] A + V \right) \frac{\partial A}{\partial x} \\ \frac{\partial A}{\partial x} &= \frac{\partial Q}{\partial x} \frac{1}{\frac{2}{3} \frac{1}{n} R^{-1/3} S_f^{1/2} \left[\frac{1}{P} \left(1 - 2R \frac{\sqrt{1+m^2}}{B} \right) \right] A + V} \end{aligned}$$

$$\begin{aligned}
\frac{\partial A}{\partial x} &= \frac{\partial Q}{\partial x} \frac{1}{V\left(\frac{2}{3R}\left[\frac{1}{P}(1-2R\frac{\sqrt{1+m^2}}{B})\right]A+1\right)} \\
\frac{\partial A}{\partial x} &= \frac{\partial Q}{\partial x} \frac{1}{V\left(\frac{2}{3RP}\left[1-2R\frac{\sqrt{1+m^2}}{B}\right]A+1\right)} \\
\frac{\partial A}{\partial x} &= \frac{\partial Q}{\partial x} \frac{1}{V\left[\left(\frac{2}{3RP}-\frac{4}{3P}\frac{\sqrt{1+m^2}}{B}\right)A+1\right]} \\
\frac{\partial A}{\partial x} &= \frac{\partial Q}{\partial x} \frac{1}{V\left[\left(\frac{2A}{3RP}-\frac{4A}{3P}\frac{\sqrt{1+m^2}}{B}\right)+1\right]} \\
\frac{\partial A}{\partial x} &= \frac{\partial Q}{\partial x} \frac{1}{V\left[\left(\frac{2}{3}-\frac{4}{3}R\frac{\sqrt{1+m^2}}{B}\right)+1\right]} \tag{6.11}
\end{aligned}$$

$$: \quad (6.8) \quad (6.11)$$

$$\frac{\partial Q}{\partial t} + \frac{2Q}{A} \frac{\partial Q}{\partial x} + \left(\frac{gA}{B} - \frac{Q^2}{A^2}\right) \frac{1}{V\left[\frac{5}{3} - \frac{4R}{3} \frac{\sqrt{1+m^2}}{B}\right]} \frac{\partial Q}{\partial x} + gA(S_f - S_0) = q_l u_l$$

$$\frac{\partial Q}{\partial t} + \left(\frac{2Q}{A} + \frac{\frac{gA}{B} - \frac{Q^2}{A^2}}{V\left[\frac{5}{3} - \frac{4R}{3} \frac{\sqrt{1+m^2}}{B}\right]}\right) \frac{\partial Q}{\partial x} + gA(S_f - S_0) = q_l u_l \tag{6.12}$$

$$\frac{\partial Q}{\partial t} + \alpha \frac{\partial Q}{\partial x} + \beta = q_l u_l \tag{6.13}$$

$$\alpha = \frac{2Q}{A} \frac{\frac{gA}{B} - \frac{Q^2}{A^2}}{V\left[\frac{5}{3} - \frac{4R}{3} \frac{\sqrt{1+m^2}}{B}\right]} = \frac{2Q}{A} + \frac{\frac{gA}{B} - \frac{Q^2}{A^2}}{\frac{Q}{A} \left(\frac{5}{3} - \frac{4R}{3B} \sqrt{1+m^2}\right)} \tag{6.14}$$

$$\beta = gA(S_f - S_0) \tag{6.15}$$

:

$$\frac{\partial f}{\partial x} = \frac{f_{i+1}^j - f_i^j}{\Delta x} \tag{6.16}$$

$$\frac{\partial f}{\partial t} = \frac{f_i^{j+1} - f_i^j}{\Delta t} \quad (6.17)$$

i . $\Delta x, \Delta t$

$$\begin{aligned} & \cdot \quad j \\ & : \quad (6.23) \quad (6.27), (6.26) \end{aligned}$$

$$\frac{Q_{i+1}^{j+1} - Q_{i+1}^j}{\Delta t} + \alpha m \left(\frac{Q_{i+1}^{j+1} - Q_i^{j+1}}{\Delta x} \right) + \beta m - q_l v_l \cos \theta = 0 \quad (6.18)$$

:

$$Q_{i+1}^{j+1} = \frac{Q_{i+1}^j + \frac{\Delta t}{\Delta x} \alpha m Q_i^{j+1} - \beta m \Delta t + q_l v_l \cos \theta \Delta t}{1 + \alpha m \frac{\Delta t}{\Delta x}} \quad (6.19)$$

$$: \quad \beta m \quad \alpha m$$

$$\alpha m = \frac{\alpha_i^{j+1} + \alpha_{i+1}^j}{2} \quad (6.20)$$

$$\beta m = \frac{\beta_i^{j+1} + \beta_{i+1}^j}{2} \quad (6.21)$$

:

$$\frac{A_{i+1}^{j+1} - A_{i+1}^j}{\Delta t} + \frac{Q_{i+1}^j - Q_i^j}{\Delta x} = q_l$$

:

$$A_{i+1}^{j+1} = A_{i+1}^j - \frac{\Delta t}{\Delta x} (Q_{i+1}^j - Q_i^j) + \Delta t q_l \quad (6.22)$$

:

: -

:

$$Q(0, t) = f(t) \quad (6.23)$$

: -

:

$$Q(x, 0) = Q_0 \quad (6.24)$$

$$y(x, 0) = y_0 \quad (6.25)$$

$$\Delta t \leq \frac{\sqrt{1+2Fr_0}-1}{Fr_0 \frac{gS_0}{V_0}} \quad (6.26)$$

$$\Delta x_{\max} = (\sqrt{1+2Fr_0}-1)(1+Fr_0) \frac{y_0}{S_0} \quad (6.27)$$

16D,14D

MD

$$y_0 = 0.263m, Q_0 = 0.1m^3 / \text{sec}, b = 1m, m = 1.5, S = 0.00075$$

$$A_0 = (1 + 1.5 * 0.263) * 0.263 = 0.367m^2$$

$$V_0 = \frac{Q_0}{A_0} = \frac{0.1}{0.367} = 0.27m / \text{sec}$$

$$Fr_0 = \frac{V_0}{\sqrt{gy_0}} = \frac{0.27}{\sqrt{9.81 * 0.263}} = 0.1681 < 1 \quad : (6.36)$$

$$\Delta t = \frac{\sqrt{1+2Fr_0}-1}{Fr_0 \frac{gS_0}{V_0}} = \frac{\sqrt{1+2*0.1681}-1}{0.1681 * \frac{9.81 * 0.00075}{0.27}} = 34.04 \text{ sec} \quad : (6.37)$$

$$\Delta x_{\max} = (\sqrt{1+2*0.1681}-1)(1+0.1681) \frac{0.263}{0.00075} = 63.87m$$

: 6854 m 14D

$$L = \frac{6854}{63.87} = 107.3$$

: 108 16D

$$L = \frac{6854}{108} = 63.46m$$

34.04

108

63.46

:MD

16D

(6-1)

t	Q	h
0	0.1	0.263
2	0.109	0.263
4	0.19	0.351
6	0.345	0.481
8	0.345	0.481
10	0.345	0.481
12	0.34	0.454

:14D :

:

$$y_0 = 0.214m, Q_0 = 0.15m^3 / \text{sec}, b = 2.5m, m = 1.5, S = 0.0006$$

$$A_0 = (2.5 + 1.5 * 0.214) * 0.214 = 0.604m^2$$

:

$$V_0 = \frac{Q_0}{A_0} = \frac{0.15}{0.604} = 0.248m / \text{sec}$$

:

$$Fr_0 = \frac{V_0}{\sqrt{gy_0}} = \frac{0.248}{\sqrt{9.81 * 0.214}} = 0.1712 < 1$$

: (6.36)

-۳

$$\Delta t = \frac{\sqrt{1 + 2Fr_0} - 1}{\frac{Fr_0}{62} \frac{gS_0}{V_0}} = \frac{\sqrt{1 + 2 * 0.1712} - 1}{\frac{0.1712 * \frac{9.81 * 0.0006}{0.248}}{2}} = 39.65 \text{ sec}$$

14D

: (6.37)

-۴

$$\Delta x_{\max} = (\sqrt{1 + 2 * 0.1712} - 1)(1 + 0.1712) \frac{0.214}{0.0006} = 66.26m$$

:

2850m 14D

$$L = \frac{2850}{66.26} = 43.01m$$

•

•

43 14D

$$L = \frac{2850}{43} = 66.27m$$

43

66.27 40

:MD

14D

(6-2)

t	Q	h
0	0.15	0.214
2	13.43	1.792
4	27.44	2.927
6	34.61	3.44
8	36.27	3.633
10	33.39	3.567
12	29.23	3.383
14	24.37	3.17
16	19.50	2.876
18	15.23	2.58
20	11.62	2.294
22	8.67	2.011
24	6.34	1.749
26	4.61	1.516
28	3.45	1.33
30	2.47	1.146
32	1.77	0.962
34	1.06	0.778
36	0.91	0.642
38	0.76	0.587
40	0.46	0.467

: MD :

:

$$y_0 = 0.516m, Q_0 = 0.81m^3 / sec, b = 2.5m, m = 1.5, S = 0.00075$$

$$A_0 = (2.5 + 1.5 * 0.516) * 0.516 = 1.689m^2$$

:

$$V_0 = \frac{Q_0}{A_0} = \frac{0.81}{1.689} = 0.48m/sec$$

:

$$Fr_0 = \frac{V_0}{\sqrt{gy_0}} = \frac{0.48}{\sqrt{9.81 * 0.516}} = 0.2133 < 1$$

: (6.36) -o

$$\Delta t = \frac{\sqrt{1 + 2Fr_0} - 1}{Fr_0 \frac{gS_0}{62V_0}} = \frac{\sqrt{1 + 2 * 0.21} - 1}{0.21 * \frac{9.81 * 0.00075}{0.48}} = 59.38sec$$

MD

.

$$: (6.37) \quad -\gamma$$

$$\Delta x_{max} = (\sqrt{1 + 2 * 0.2133} - 1)(1 + 0.2133) \frac{0.516}{0.00075} = 164.9m$$

: 10200m MD

$$L = \frac{10200}{164.9} = 61.85m$$

$$: \quad 64 \quad MD$$

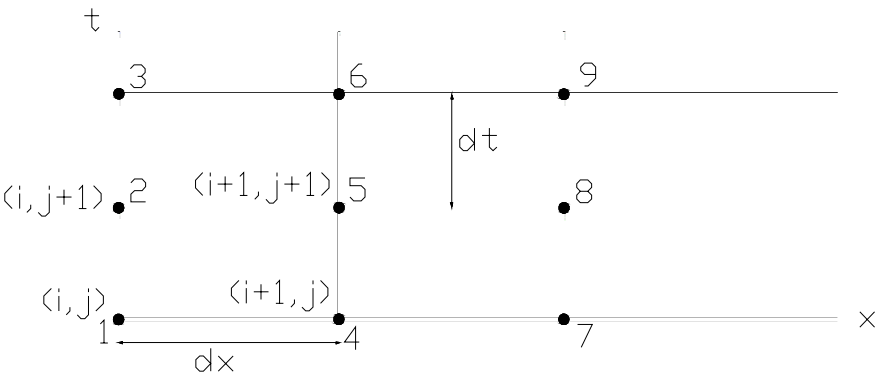
$$L = \frac{10200}{64} = 160m$$

$$16D \quad 64$$

$$14D \quad 23 \quad MD$$

.52

(6-2)



(6-2)

(4) (1)

(3) (2) ()

(6.25),(6.24) (4) (2) $\beta m \quad \alpha m$ $-\gamma$

(5) (6.29)

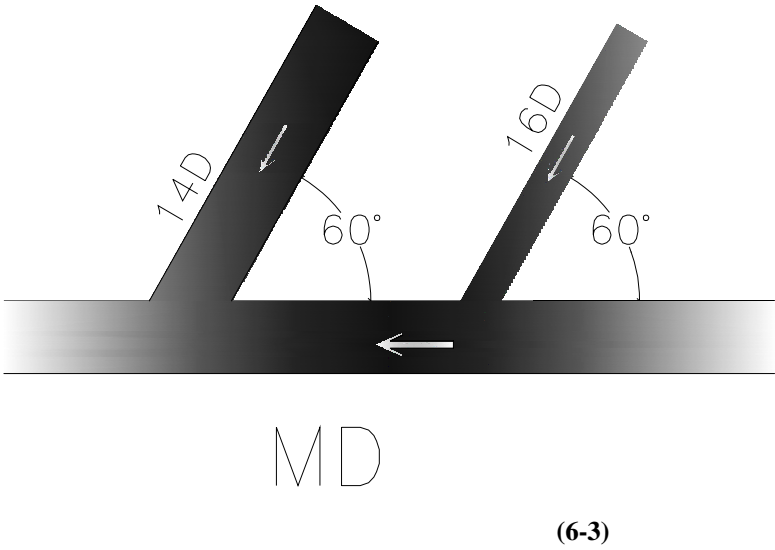
(6.32) $-\lambda$

$-\rho$

$-\lambda$

16D 14D MD

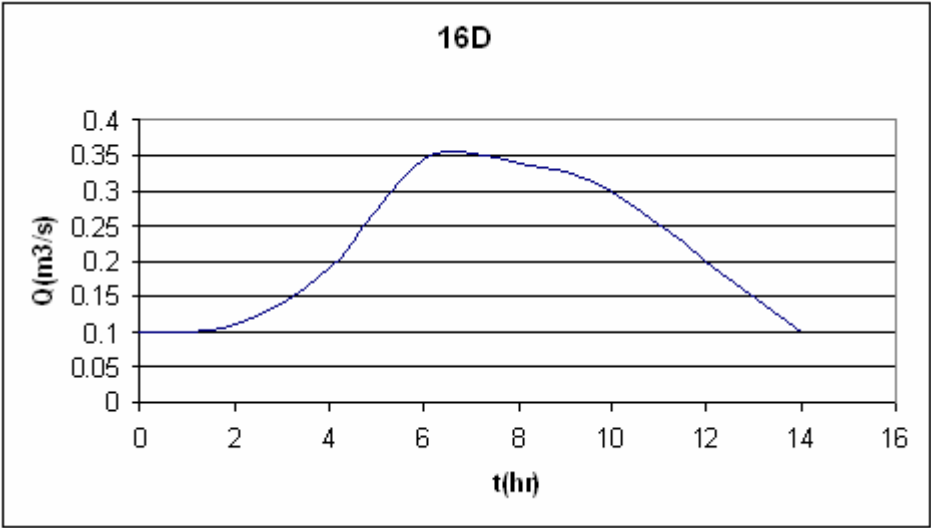
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16D

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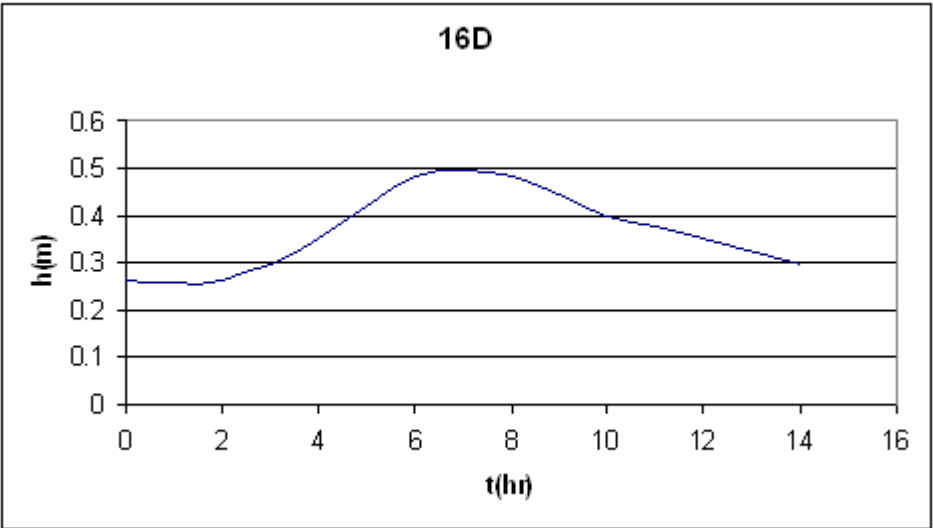


16D

(6-4)

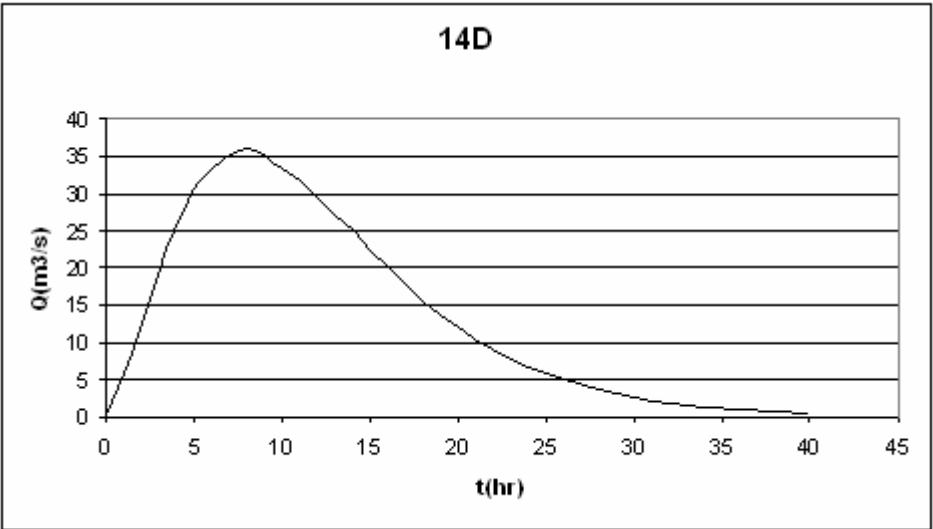
16D

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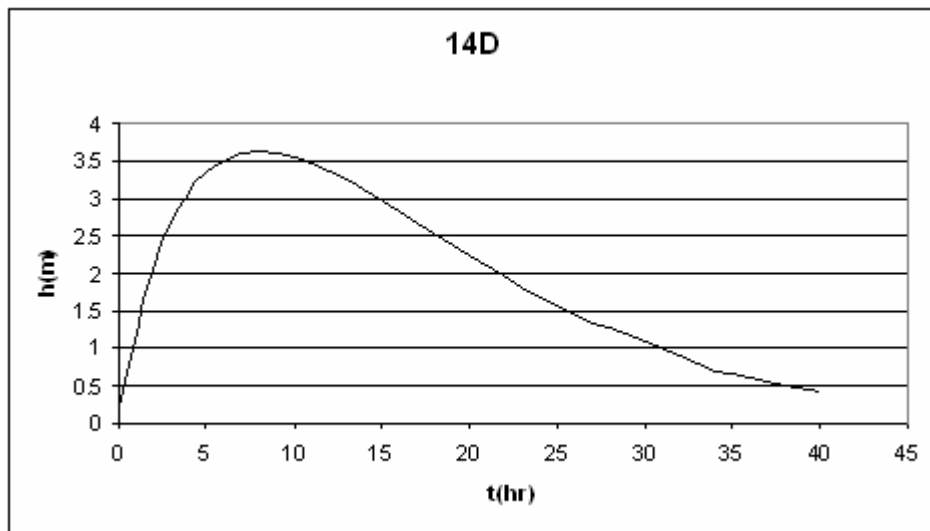
16D (6-5)

14D



14D (6-6)

14D

**14D****(6-7)**

الفصل السابع

النتائج والتعليق

Visual Basic

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بيانات المدخلات الرئيسية

بيانات المدخلات الرئيسية

قيم الترددات و الأعماق وفق خطوة الزمان و المكان المختاريتين

الترددات

قبل إضافة الراءد

بعد إضافة الراءد

الأعماق

قبل إضافة الراءد

بعد إضافة الراءد

بيانات الراءد عند انتقاله مع المدخلات الرئيسية

تدقيق الراءد

أعماق الماء للراءد

بيانات المدخلات الرئيسية

عرض القاعدة

ميل الجوانب

الميل الطولي

الخشونة

الفاصل الزمني

عدد القراءات

طول القناة

عدد الراءد

عدد القراءات للراءد

calc

النتائج النهائية

الخروج من البرنامج

(7-1)

بيانات المدخلات الرئيسية

بيانات المدخلات الرئيسية

قيم الترددات و الأعماق وفق خطوة الزمان و المكان المختاريتين

الترددات

قبل إضافة الراءد

بعد إضافة الراءد

الأعماق

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الخشونة

الفاصل الزمني

عدد القراءات

طول القناة

عدد الراءد

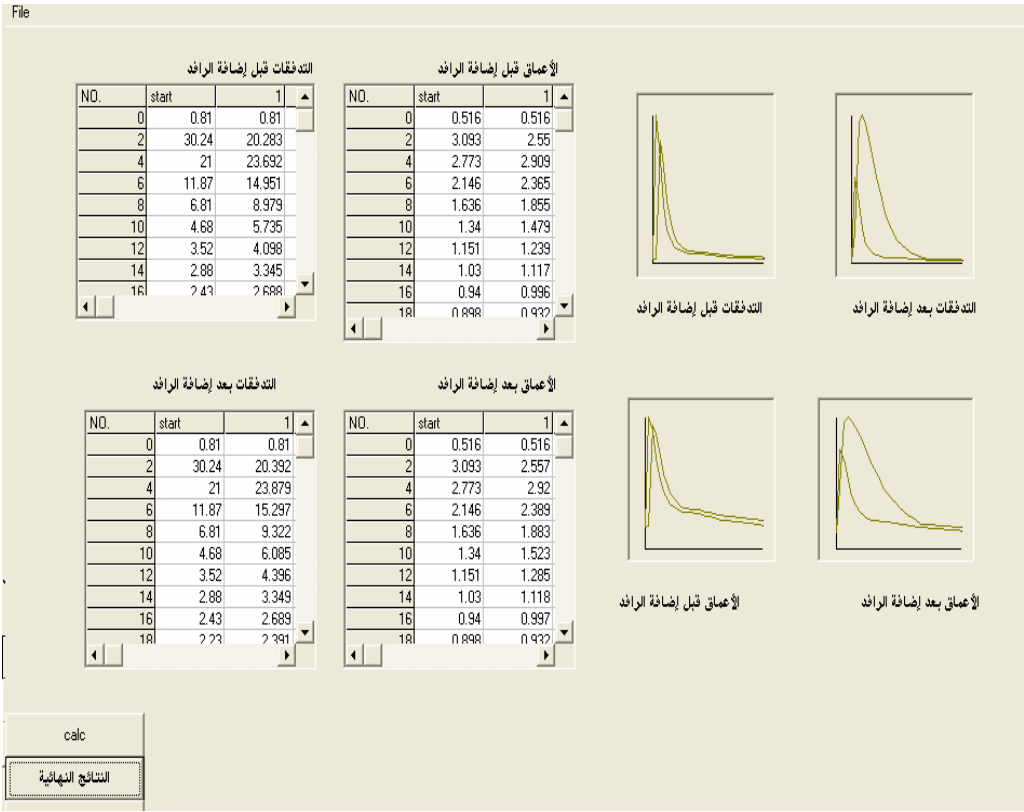
عدد القراءات للراءد

calc

النتائج النهائية

الخروج من البرنامج

(7-2)



(7-3)

16D 14D

MD

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)16D

MD

MD

MD

()14D

MD

(7-1)

64	52	23	0	t(hr)
0.81	0.81	0.81	0.81	0
0.967	3.716	20.769	30.24	2
24.953	25.579	27.283	21	4
19.668	18.385	14.831	11.87	6
12.800	11.631	8.887	6.81	8
8.115	7.284	5.688	4.68	10
5.676	5.153	4.071	3.52	12
4.288	3.996	3.322	2.88	14
3.529	3.267	2.668	2.43	16
2.850	2.622	2.383	2.23	18
2.538	2.454	2.250	2.1	20
2.481	2.400	2.199	2.05	22
2.422	2.338	2.136	1.99	24
2.358	2.274	2.074	1.93	26
2.304	2.22	2.023	1.88	28
2.227	2.144	1.95	1.81	30
2.116	2.035	1.846	1.71	32
2.007	1.929	1.746	1.61	34
1.929	1.852	1.673	1.54	36
1.827	1.752	1.573	1.44	38
1.721	1.646	1.47	1.34	40
1.675	1.603	1.433	1.31	42
1.635	1.563	1.393	1.27	44
1.591	1.52	1.353	1.23	46
1.554	1.482	1.317	1.195	48
1.516	1.446	1.282	1.16	50
1.475	1.406	1.242	1.12	52
1.432	1.364	1.199	1.08	54
1.399	1.332	1.169	1.05	56
1.368	1.3	1.137	1.02	58
1.342	1.274	1.113	0.997	60
1.314	1.246	1.085	0.97	62

16D 14D

MD

MD

16D

MD

14D

MD

MD

(7-2)

64	52	23	0	t(hr)
0.810	0.810	0.81	0.81	0
10.749	14.921	20.392	30.24	2
48.926	51.234	27.359	21	4
52.069	52.149	15.297	11.87	6
48.028	48.027	9.322	6.81	8
42.146	41.279	6.085	4.68	10
36.170	35.241	4.396	3.52	12
29.984	29.082	3.349	2.88	14
24.277	23.429	2.689	2.43	16
19.227	18.446	2.391	2.23	18
15.306	14.595	2.257	2.1	20
12.175	11.534	2.199	2.05	22
9.492	9.075	2.143	1.99	24
7.578	7.237	2.085	1.93	26
6.334	6.020	2.029	1.88	28
5.194	4.901	1.957	1.81	30
4.261	3.988	1.853	1.71	32
3.466	3.208	1.752	1.61	34
2.909	2.822	1.679	1.54	36
2.514	2.431	1.579	1.44	38
2.242	2.165	1.476	1.34	40
1.675	1.609	1.439	1.31	42
1.635	1.569	1.399	1.27	44
1.591	1.526	1.359	1.23	46
1.554	1.488	1.323	1.195	48
1.516	1.452	1.288	1.16	50
1.475	1.411	1.247	1.12	52
1.432	1.37	1.205	1.08	54
1.399	1.337	1.175	1.05	56
1.368	1.306	1.142	1.02	58
1.342	1.28	1.118	0.997	60
1.314	1.252	1.095	0.97	62

16D
14D

MD

MD

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)16D
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)14D

MD

(7-3)

64	52	23	0	t(hr)
0.516	0.516	0.516	0.516	0
0.550	1.033	2.582	3.613	2
2.914	2.978	3.057	2.773	4
2.675	2.597	2.355	2.146	6
2.189	2.100	1.846	1.636	8
1.761	1.671	1.470	1.340	10
1.470	1.400	1.237	1.151	12
1.268	1.225	1.113	1.030	14
1.147	1.104	0.992	0.940	16
1.026	0.983	0.929	0.898	18
0.962	0.944	0.902	0.870	20
0.950	0.933	0.891	0.859	22
0.938	0.921	0.877	0.845	24
0.924	0.907	0.863	0.832	26
0.913	0.895	0.835	0.820	28
0.897	0.879	0.811	0.804	30
0.872	0.854	0.787	0.779	32
0.848	0.830	0.769	0.754	34
0.830	0.812	0.743	0.736	36
0.806	0.788	0.717	0.710	38
0.781	0.762	0.707	0.683	40
0.769	0.751	0.696	0.674	42
0.759	0.741	0.696	0.663	44
0.748	0.730	0.685	0.651	46
0.739	0.720	0.675	0.641	48
0.729	0.710	0.665	0.631	50
0.718	0.699	0.653	0.619	52
0.706	0.688	0.641	0.606	54
0.697	0.679	0.632	0.597	56

0.689	0.670	0.622	0.587	58
0.682	0.663	0.615	0.580	60
0.674	0.654	0.606	0.546	62

16D 14D

MD

MD

16D

MD

14D

MD

MD

(7-4)

64	52	23	0	t(hr)
0.516	0.516	0.516	0.516	0
1.917	2.18	2.557	3.613	2
3.934	3.728	3.062	2.773	4
4.09	3.742	2.389	2.146	6
3.996	3.688	1.883	1.636	8
3.762	3.638	1.523	1.34	10
3.523	3.58	1.285	1.151	12
3.12	3.54	1.118	1.03	14
2.922	3.435	0.997	0.94	16
2.355	3.314	0.932	0.898	18
2.112	3.114	0.903	0.87	20
1.87	2.8	0.891	0.859	22
1.687	2.5	0.878	0.845	24
1.537	2.218	0.866	0.832	26
1.392	1.964	0.853	0.82	28
1.256	1.712	0.837	0.804	30
1.131	1.23	0.812	0.779	32
1.032	1.1	0.788	0.754	34
0.956	1.016	0.77	0.736	36
0.9	0.939	0.745	0.71	38
0.766	0.883	0.718	0.683	40
0.768	0.753	0.708	0.674	42
0.759	0.743	0.697	0.663	44
0.748	0.731	0.686	0.651	46
0.739	0.721	0.676	0.641	48
0.729	0.712	0.667	0.631	50
0.719	0.701	0.655	0.619	52
0.706	0.689	0.643	0.606	54
0.697	0.68	0.631	0.597	56
0.689	0.672	0.624	0.587	58

0.682	0.664	0.617	0.58	60
0.674	0.656	0.608	0.546	62

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(7-4)

$Q_{\max} = 30.24m^3 / s$

62

x=64

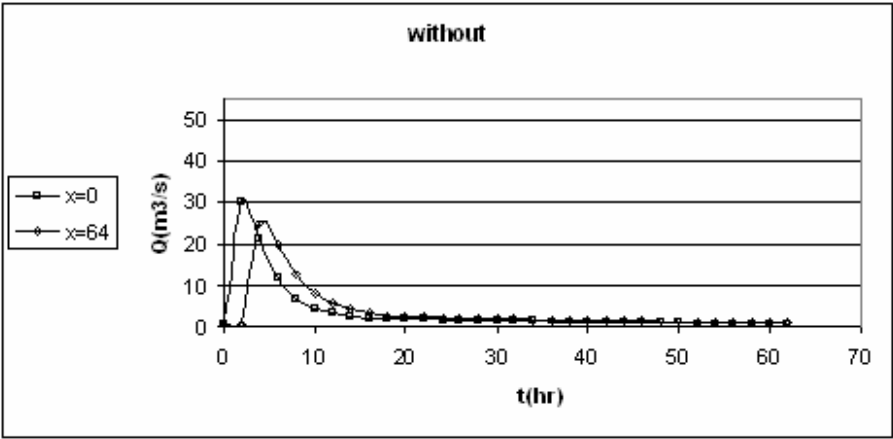
$Q = 0.97m^3 / s$

$Q_{\max} = 24.95m^3 / s$

12

12

.(Lag time)

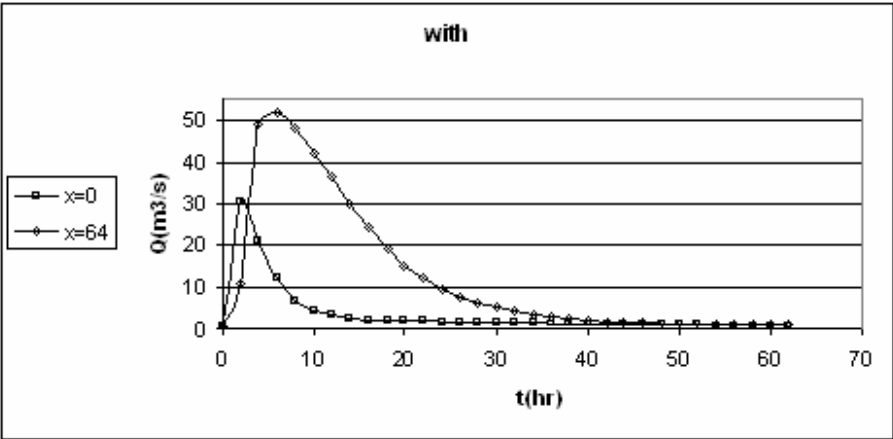


(7-4)

(7-5)

8400m 3662m

$Q_{\max} = 52.069m^3 / s$



(7-5)

23

(7-6)

MD

16D

$Q_{\max} = 27.238m^3 / s$

x=23

16D

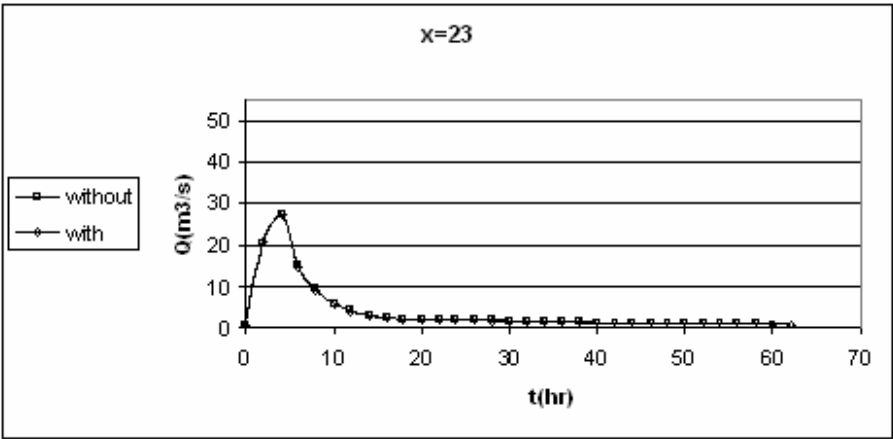
16D

52

16D

$Q_{\max} = 27.359m^3 / s$

53



23

(7-6)

$Q_{\max} = 25.579m^3 / s$

x=52

(7-7)

52

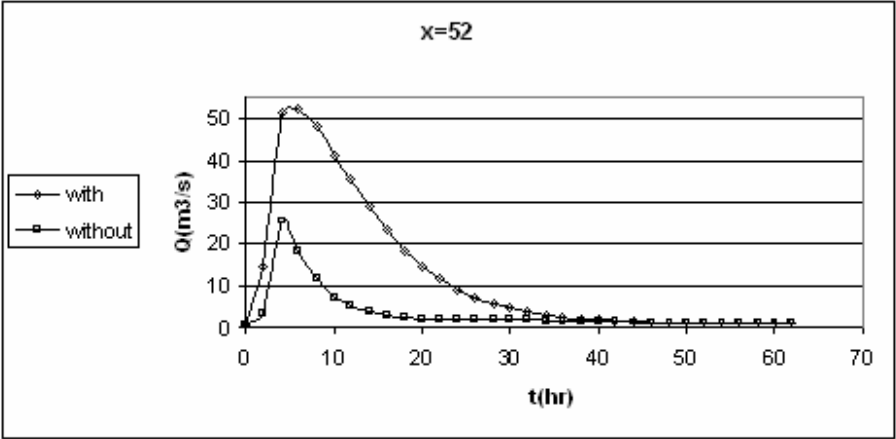
52

MD

14D

$$Q_{\max} = 52.149m^3 / s$$

51



52

(7-7)

(7-8)

t=0

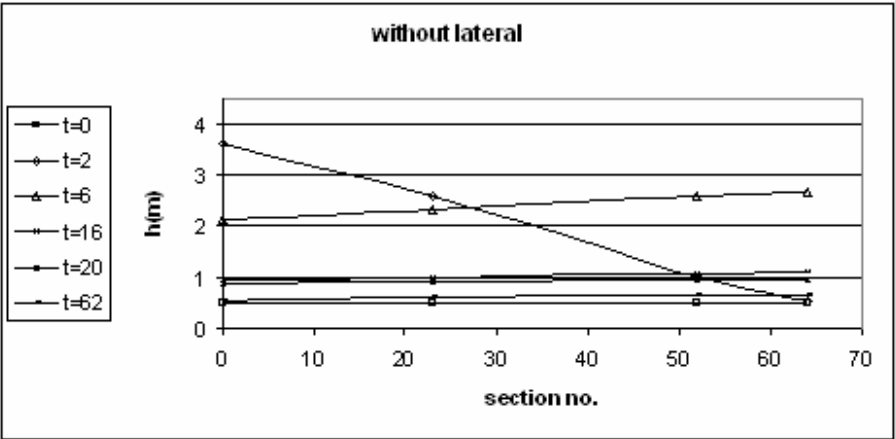
t=2hr

t=10hr

t=20hr

t=62hr

62



(7-8)

:

(7-9)

$t=0$

$t=2hr$

MD

14D

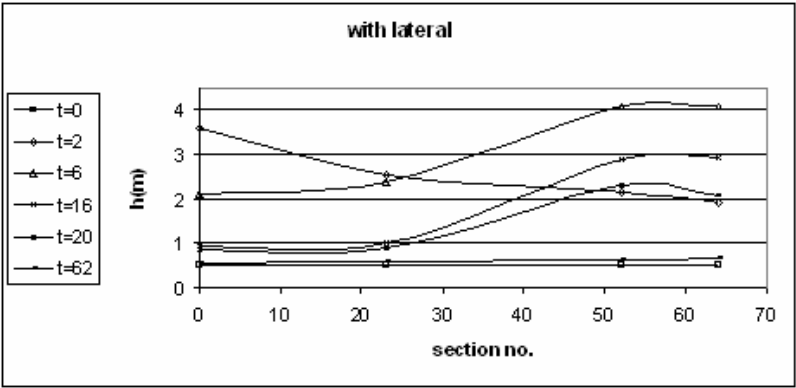
$t=10hr$

52

$t=20hr$

62

$t=62hr$



(7-9)

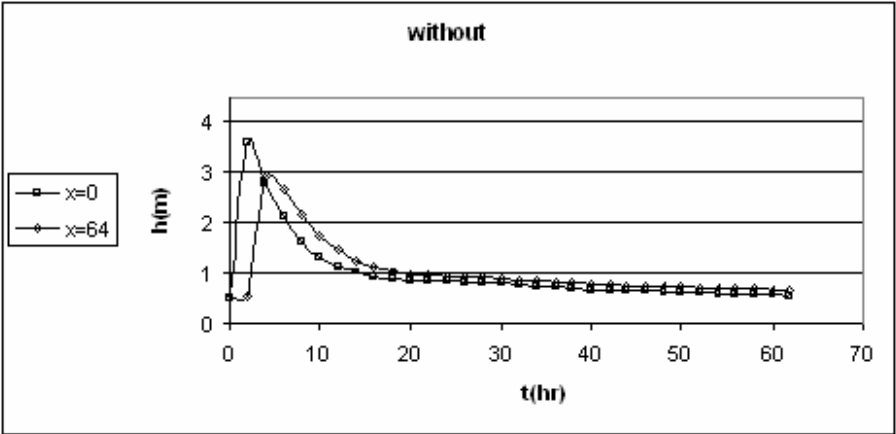
(7-10)

12

$h = 3.893m$

18

$h = 2.914m$ $x=64$

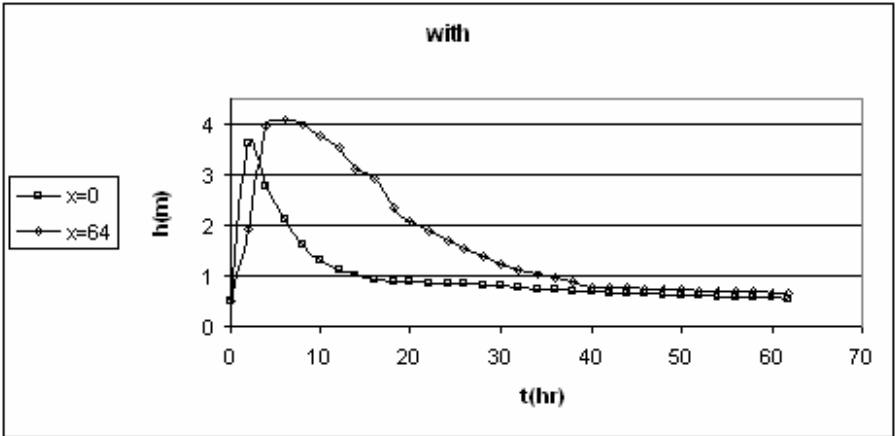


(7-10)

(7-11)

4

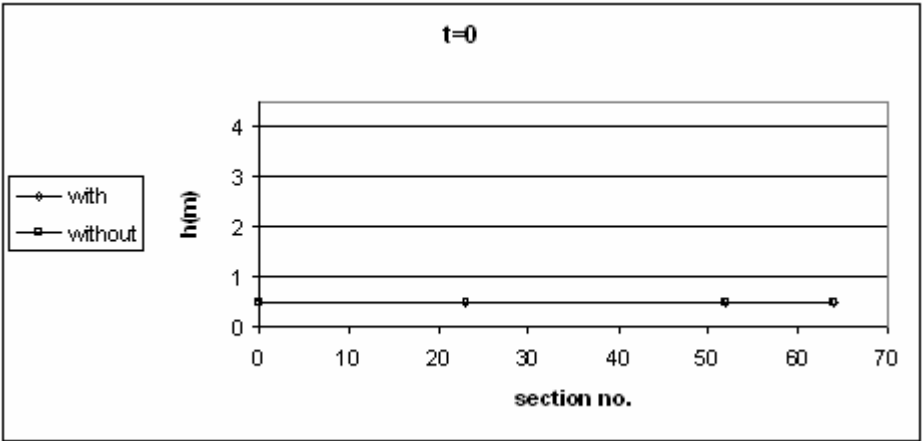
$h = 4.099m$



(7-11))

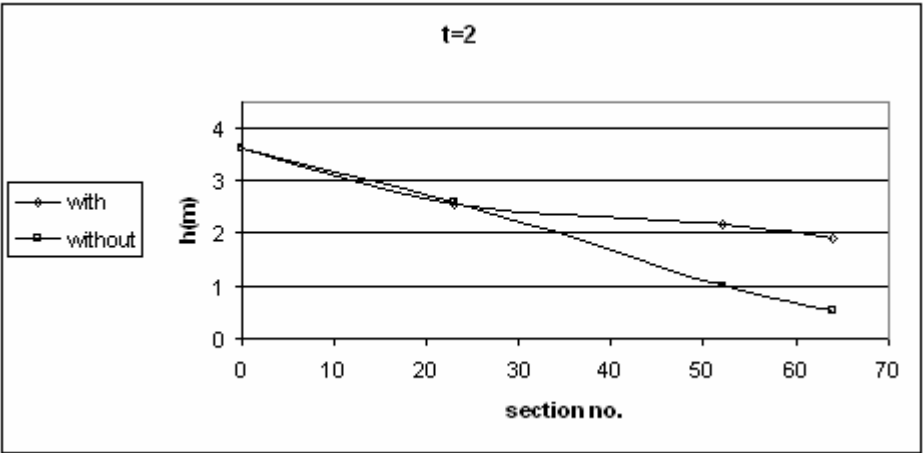
$t=0hr$

(7-12)



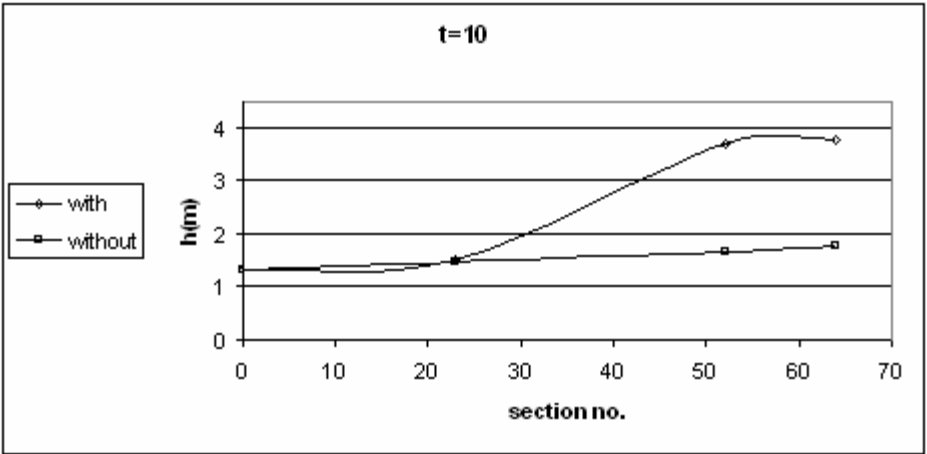
t=0hr (7-12)

t=2hr (7-13)

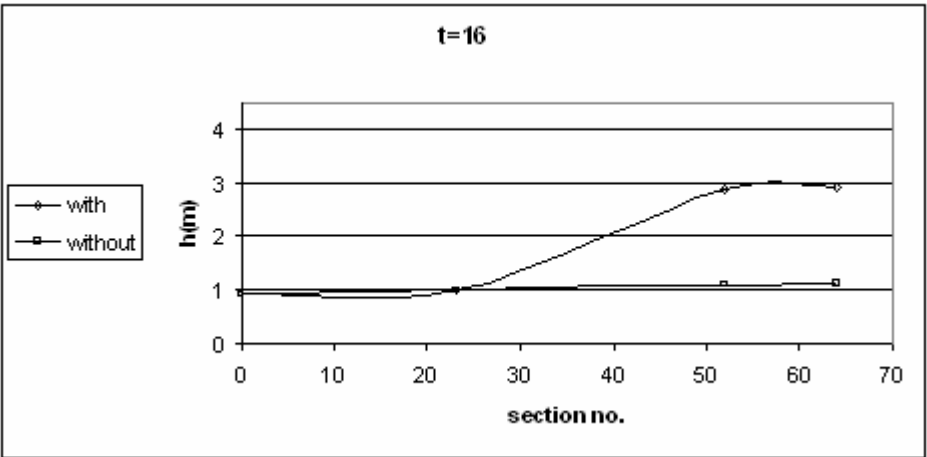


t=2hr (7-13)

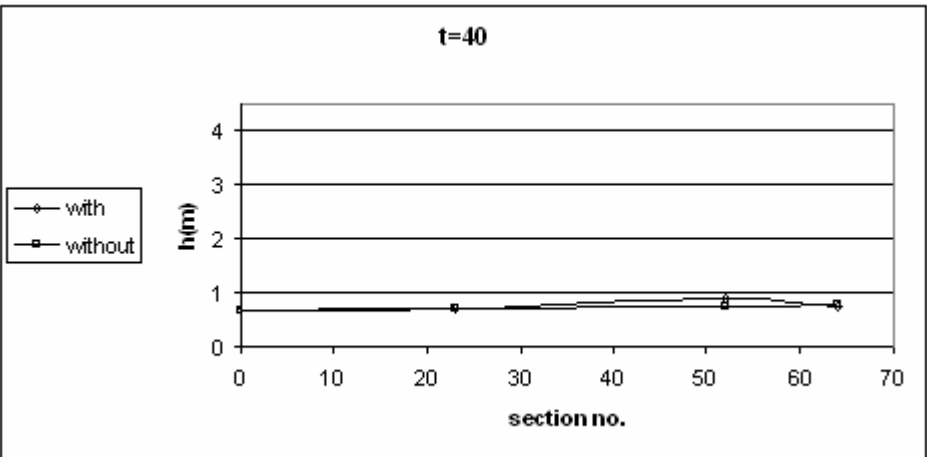
t=10hr (7-14)



t=10hr (7-14)

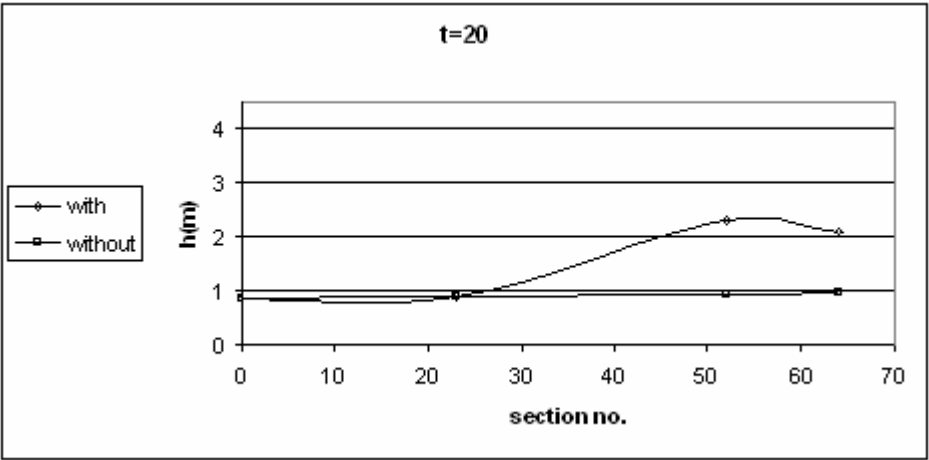


t=16hr (7-15)



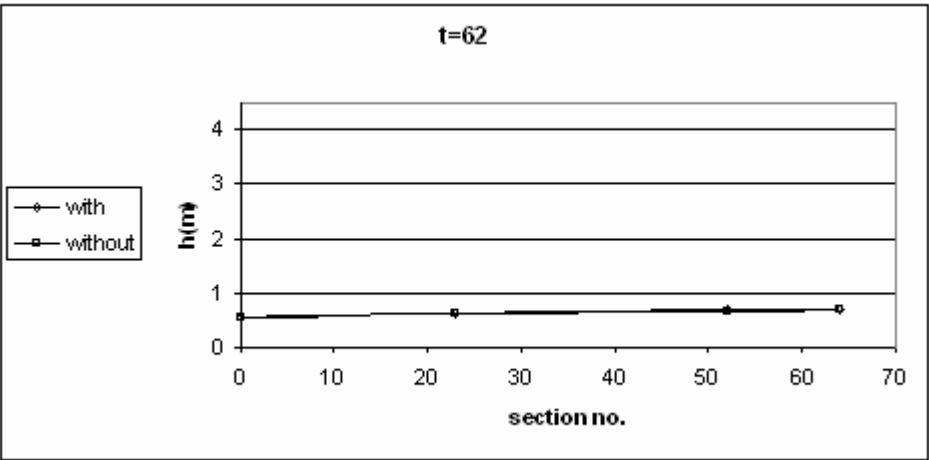
t=40hr (7-16)

t=20hr (7-17)
14D



t=20hr (7-17)

t=62hr (7-18)



t=62hr (7-18)

:

MD

(7-5)

52	23	0	t(hr)
0.81	0.81	0.81	0
3.716	20.769	30.24	2
25.579	27.283	21	4
18.385	14.831	11.87	6
11.631	8.887	6.81	8
7.284	5.688	4.68	10
5.153	4.071	3.52	12
3.996	3.322	2.88	14
3.267	2.668	2.43	16
2.622	2.383	2.23	18
2.454	2.25	2.1	20
2.4	2.199	2.05	22
2.338	2.136	1.99	24
2.274	2.074	1.93	26
2.22	2.023	1.88	28
2.144	1.95	1.81	30
2.035	1.846	1.71	32
1.929	1.746	1.61	34
1.852	1.673	1.54	36
1.752	1.573	1.44	38
1.646	1.47	1.34	40
1.603	1.433	1.31	42
1.563	1.393	1.27	44
1.52	1.353	1.23	46
1.482	1.317	1.195	48
1.446	1.282	1.16	50
1.406	1.242	1.12	52
1.364	1.199	1.08	54
1.332	1.169	1.05	56
1.3	1.137	1.02	58
1.274	1.113	0.997	60

23

MD

14D

53

16D

MD**(7-6)**

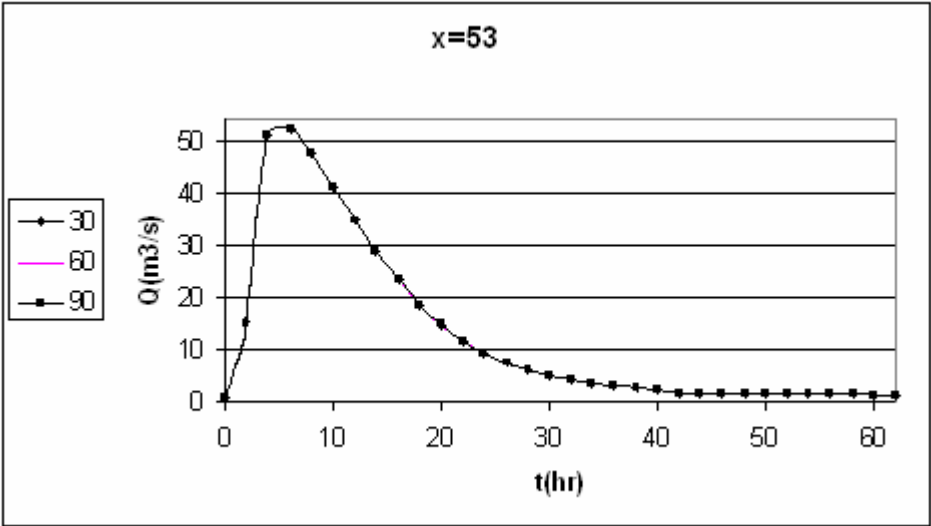
52	23	T
0.96	0.91	0
17.146	20.878	2
53.019	27.473	4
52.995	15.176	6
47.901	9.232	8
40.674	6.033	10
34.383	4.411	12
28.366	3.322	14
22.767	2.668	16
17.852	2.383	18
14.074	2.25	20
11.07	2.199	22
8.678	2.136	24
6.884	2.074	26
5.67	2.023	28
4.614	1.95	30
3.805	1.846	32
2.989	1.746	34
2.762	1.673	36
2.512	1.573	38
2.106	1.47	40
1.603	1.433	42
1.563	1.393	44
1.52	1.353	46
1.482	1.317	48
1.446	1.282	50
1.406	1.242	52
1.364	1.199	54
1.332	1.169	56
1.3	1.137	58
1.274	1.113	60

4.12m

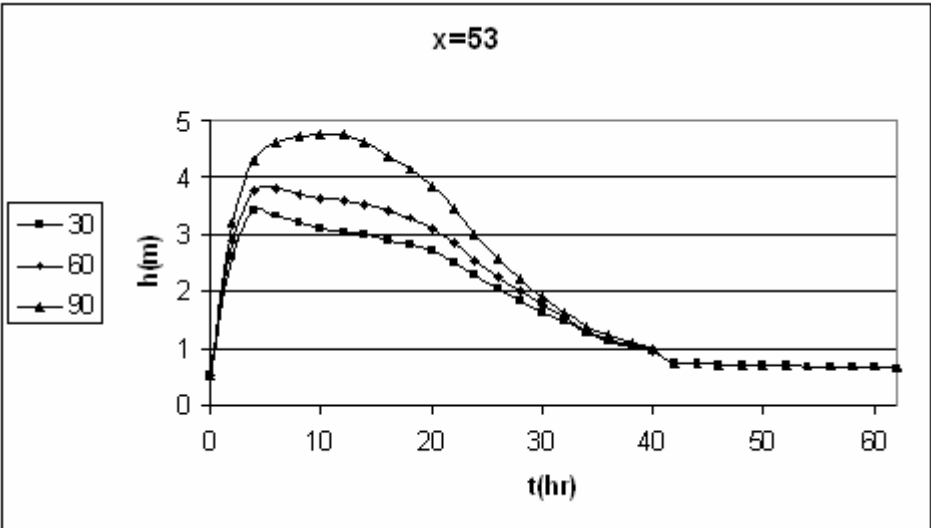
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14D MD
90 30 60



(7-19)

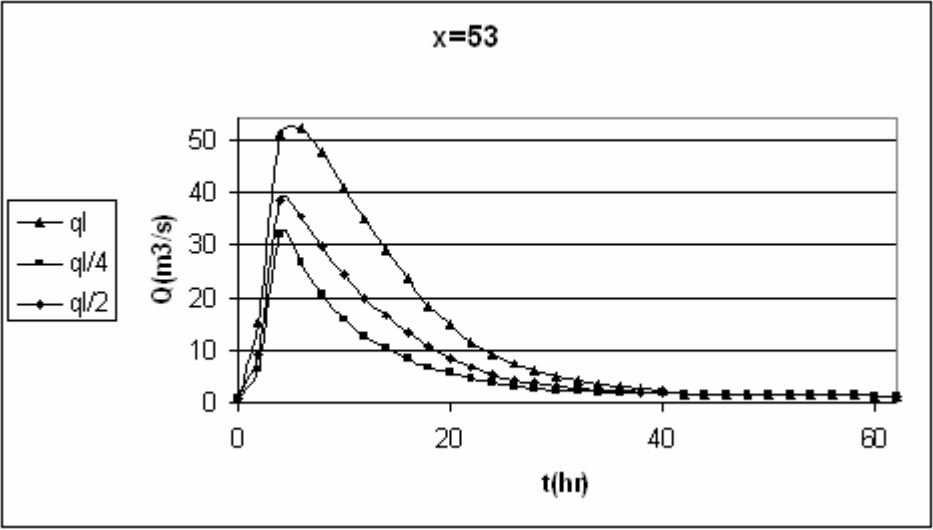


(7-20)

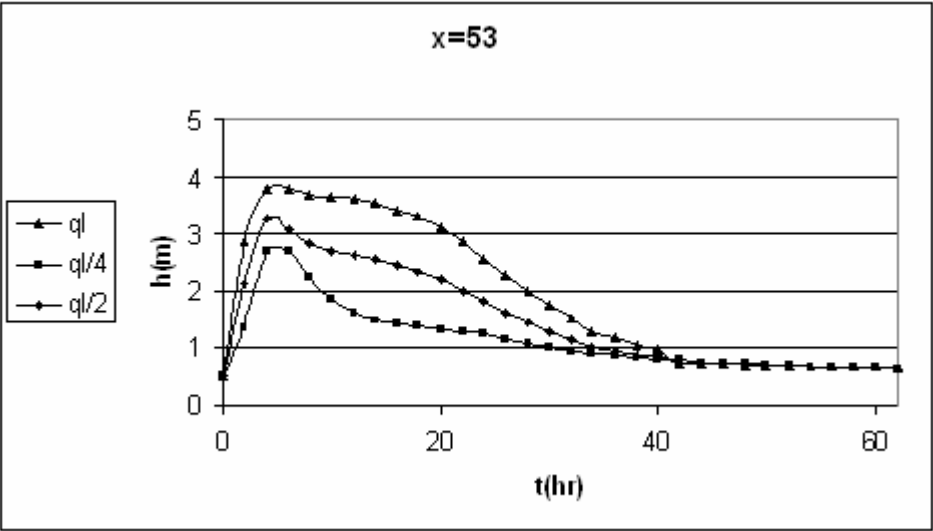
: - -

14D MD
60)
: (

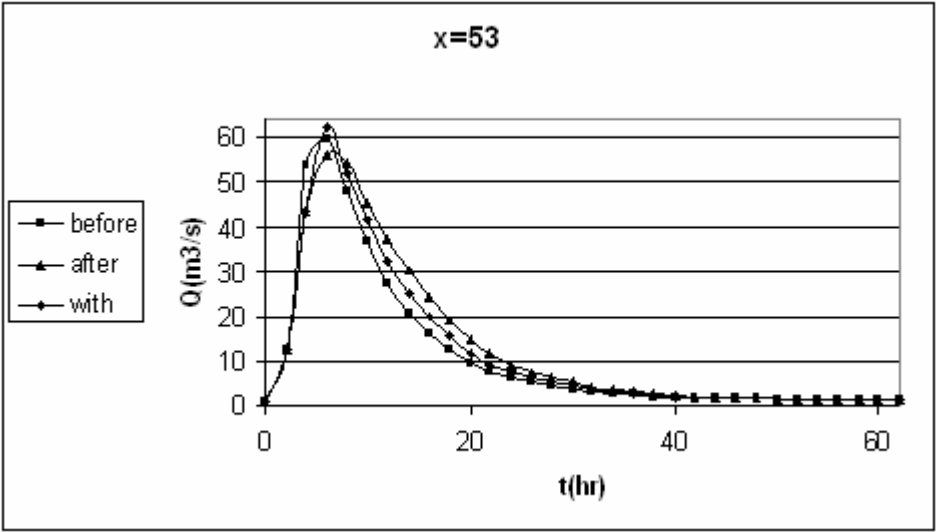
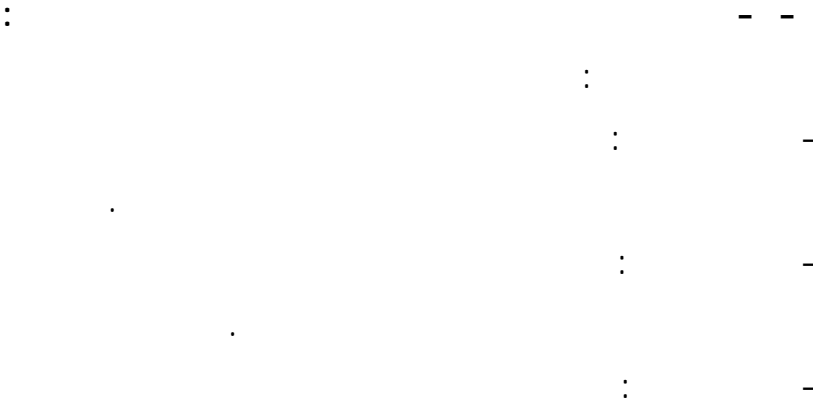
Q_{14D}	Q_{MD}	-
$Q_{14D} / 2$	Q_{MD}	-
$Q_{14D} / 4$	Q_{MD}	-



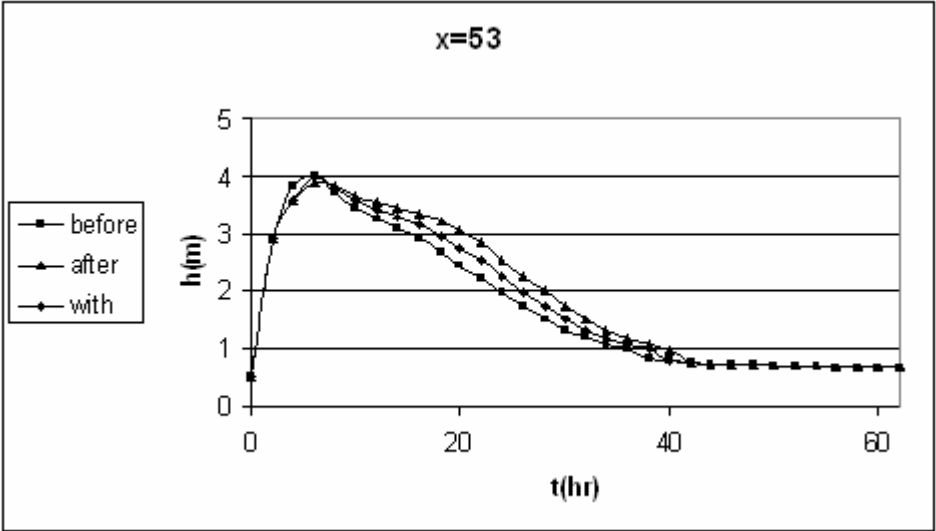
(7-21)



(7-22)



(7-23)



(7-24)

$$\begin{aligned} & \left(\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right) \left(\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right) \\ & \left(\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right) \left(\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right) \\ & \left(\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right) \left(\begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right) \end{aligned}$$

الفصل الثامن

المناقشة والخاتمة

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الفصل التاسع

التوصيات والملاحظات

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المراجع

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Abstract

A design of hydraulic structure (siphon, culvert,.....etc) on a watercourse needs, usually, two values measurements; discharge and depth in that place of design. but in that positions needed for design these measurements are not available, mostly ,especially in watercourse for receiving water floods.

Regarding to that flood wave which is created in watercourse terminates gradually due to the reduction in the values of maximum flow and depth until it terminates totally in certain distance. thus there is necessity, for studying flood wave movements ,arises along with watercourses, especially in the position of meeting with lateral inflow.

The purpose of this study is to determine the specifications of flow in a certain sections along with watercourse, that is to take the required procedures and measurements, and reduce costs on other hand .

Flood wave movement obeys, as known, to the conditions of unsteady flow.

Therefore, the research based on the use of finite difference method.

The research on flood wave movement in main stream with lateral inflow(tributary), the range of changes in discharges and depths which starting from the point of meeting with lateral inflow and what follows this point ,that are based on known hydrograph inflow in the start point of each one.

This study was applied to open channel networks(in irrigation system ML-2)in the southern Aleppo lands in the north of Syria.

Confirmation

We confirm that the research entitled:

" Effects of flood influx on channel networks"

witness that the described work in this treatise is the result of scientific search conduct by the candidate Eng.. Lama Baidak , under the supervision of Dr. Mohammad Amin Shaghala (University of Aleppo) and Dr. Nada Al Tunji (University of Aleppo), to obtain Master's degree in Hydraulic Engineering department in faculty of Civil Engineering . Every reference taken from another researches about my Master's title is mentioned and reported in my research

Candidate	supervisor	supervisor
Eng: Lama Baidak	Dr Mohammad Amin Shaghala	Dr.Nada Al Tunji

Declaration

I hereby certify that this work:

" Effects of flood influx on channel networks"

has not been accepted for any degree, or is not submitted to any other degree.

Candidate	supervisor	supervisor
Eng: Lama Baidak	Dr Mohammad Amin Shaghala	Dr.Nada Al Tunji

University of Aleppo
Faculty Of Civil Engineering
Department Of Hydraulic Engineering



Effects of Flood Influx on Channel Networks

Research Prepared for Master Degree in Hydraulic Engineering

**Prepared by
Eng: Lama Baydak**

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Faculty Of Civil Engineering - Aleppo University

2009

Aleppo University
Faculty Of Civil Engineering
Hydraulic Engineering Department



Effects of Flood Influx on Channel Networks

Research Prepared for Master Degree in Hydraulic Engineering

**Prepared by
Eng: Lama Baidak**

2009